Numerical Analysis. Laurea Magistrale, Telecommunications Engineering. AA 2007-2008, 24th July 2008.

Question 1. Consider the model IVP

ODE:
$$q'(t) = \beta q(t), t \in [0, 1], \beta \le 0,$$

IC: $q(0) = 1$ (1)

and the Taylor method of order p to solve it:

$$\left. \begin{array}{l} q^{n+1} = q^n + h\phi(t^n, q^n, h) , \\ \phi(t^n, q^n, h) = q^{(1)}(t^n) + \frac{1}{2}h^1 q^{(2)}(t^n) + \ldots + \frac{1}{p!}h^{p-1}q^{(n)}(t^n) . \end{array} \right\}$$
(2)

Find the local truncation error for the case p = 2.

Question 2. Consider a model for an infinite transmission line given by the PDEs

$$\left. \begin{array}{l} \partial_t I(x,t) + \frac{1}{L} \partial_x E(x,t) = -\frac{R}{L} I , \\ \partial_t E(x,t) + \frac{1}{C} \partial_x I(x,t) = -\frac{G}{C} E . \end{array} \right\} \tag{3}$$

where the unknowns are I and E. Assume the source terms are identically zero.

- (a) Find the eigenvalues of the system and consider them in increasing order.
- (b) Find the right eigenvectors R_i with scaling factors α_1, α_2 .
- (c) Find the left eigenvectors L_i with scaling factors γ_1 , γ_2 .
- (d) Assuming $\alpha_1 = 1$, $\alpha_2 = 1$, find the scaling for γ_1 , γ_2 such that the left and right eigenvectors are orthonormal, that is $L_i R_j = 1$ if $i = j \in L_i R_j = 0$ if $i \neq j$.
- (e) Find the characteristic variables.

Question 3. Recall that the finite volume formulation for non-linear systems in one space dimension with source terms

$$\partial_t q + \partial_x f(q) = s(q) , \qquad (4)$$

has the form

$$q_i^{n+1} = q_i^n - \frac{\Delta t}{\Delta x} [f_{i+\frac{1}{2}} - f_{i-\frac{1}{2}}] + \Delta t s_i .$$
(5)

Recall also that each term is to be interpreted as follows

$$q_i^n = \frac{1}{\Delta x} \int_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} q(x, t^n) dx , \qquad (6)$$

$$f_{i+\frac{1}{2}} = \frac{1}{\Delta t} \int_0^{\Delta t} f(q(x_{i+\frac{1}{2}}, t)) dt , \qquad (7)$$

and

$$s_{i} = \frac{1}{\Delta t} \frac{1}{\Delta x} \int_{0}^{\Delta t} \int_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} s(q_{i}(x,t)) dx dt .$$
(8)

Consider in particular the model advection-reaction equation

$$\partial_t q + \lambda \partial_x q = \beta q , f(q) = \lambda q; s(q) = \beta q , \qquad (9)$$

where $\lambda > 0$ and $\beta \le 0$ are two constants Consider a numerical scheme constructed as follows: (i) for the numerical flux use Godunov upwind method, that is, evaluate the flux integral at the interface $x_{i+\frac{1}{2}}$ by assuming a constant integrand in (7) equal to λq_i^n (for $\lambda > 0$); (ii) for the numerical source evaluate the source double integral (8) by assuming a "frozen" value $\frac{1}{2}(q_{i-1}^n + q_i^n)$ for $q_i(x, t)$. • (a) verify that the resulting numerical scheme for (9) is

$$q_i^{n+1} = q_i^n - c(q_i^n - q_{i-1}^n) + \frac{1}{2}r(q_{i-1}^n + q_i^n) .$$
(10)

- (b) write the scheme in the form $q_i^{n+1} = \sum_{k=-l}^{k=1} b_k q_{i+k}^n$ and analyze the monotonicity of the scheme for $\lambda > 0$.
- (c) analyze the linear stability of the scheme using the von Neumann method. Discuss your results.

Question 4. Consider the initial-boundary problem

PDE:
$$\partial_t q(x,t) = \alpha \partial_x^{(2)} q(x,t)$$
, $x \in (0,b)$, $t > 0$,
IC: $q(x,0) = q^{(0)}(x)$, $x \in (0,b)$,
BCs: $q(0,t) = q_0(t)$, $q(b,t) = q_b(t)$, $t \ge 0$.
(11)

Take b = 1, $\alpha = 1$ and initial condition

$$q(x,0) = \begin{cases} q_L = 1 & \text{if } x < 1/2 , \\ q_R = 0 & \text{if } x > 1/2 , \end{cases}$$
(12)

As boundary conditions take $q_0(t) = 1$ and $q_b(t) = 0$. Discretize the domain by a finite difference mesh with M=4 interior points.

- (a) Apply "by hand" the explicit FTCS scheme with D = 0.4 for 5 time steps and construct a table of solution values for each time step.
- (b) Construct the implicit FTCS scheme for the same problem and write the resulting linear system in matrix form (do not solve it).

Question 5. Consider the elliptic Boundary Value Problem

$$\partial_{x}^{(2)}q(x,y) + \partial_{y}^{(2)}q(x,y) = 0, \ (x,y) \in [0,1] \times [0,1],
q(x,0) = q_{B}(x) = 1 - x, \ x \in [0,1],
q(x,b) = q_{T}(x) = 1 - x, \ x \in [0,1],
q(0,y) = q_{L}(y) = 1, \ y \in [0,1],
q(a,y) = q_{R}(y) = 0, \ y \in [0,1]$$
(13)

and the finite difference five-point formula

$$q_{i,j} = \frac{q_{i-1,j} + q_{i+1,j} + q_{i,j-1} + q_{i,j+1}}{4} , \qquad (14)$$

with $\Delta x = \Delta y = 1/3$.

- (a) Illustrate through a drawing the geometric situation (domain, discretization and notation), clearly identifying the vector of unknowns **X**.
- (b) Assuming guess values $x_l^{(0)} = 1/4$, for l = 1, 2, 3, 4, apply the Jacobi method for 3 iterations, measuring the norm of the error $\mathbf{E}^{(k+1)} = ||\mathbf{X}^{(k+1)} \mathbf{X}^{(k)}||$ at each iteration k. As a norm of a vector $\mathbf{V} = [v_1, v_2, \ldots, v_m]$ use $||\mathbf{V}|| = max_l(|v_l|)$. Put all results on a table (all calculations to be made by hand).