

# > Soluzioni del compito di Calcolo Numerico del 29 luglio 2003

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> restart:

> with(LinearAlgebra):

## - Esercizio 1

[ matrice identità e vettori canonici della base usati per i conti successivi

> e1, e2, e3, e4 := <1, 0, 0, 0>, <0, 1, 0, 0>, <0, 0, 1, 0>, <0, 0, 0, 1>;

$$e_1, e_2, e_3, e_4 := \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

[ Matrice identità

> ID := <e1|e2|e3|e4>;

$$ID := \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

[ Matrice iniziale

> A := Matrix([[ -3, 2, 11, 48],  
[12, -24, -36, -48],  
[ -6, 24, -6, -12],  
[ -4, 2, 36, 10]]);

$$A := \begin{bmatrix} -3 & 2 & 11 & 48 \\ 12 & -24 & -36 & -48 \\ -6 & 24 & -6 & -12 \\ -4 & 2 & 36 & 10 \end{bmatrix}$$

> A0 := A :

[ Matrice di permutazione

> P1 := <e2|e1|e3|e4>;

$$P1 := \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Scambio la prima con la seconda riga

> P1A0 := P1.A0;

$$P1A0 := \begin{bmatrix} 12 & -24 & -36 & -48 \\ -3 & 2 & 11 & 48 \\ -6 & 24 & -6 & -12 \\ -4 & 2 & 36 & 10 \end{bmatrix}$$

Matrice di eliminazione

> L1 := ID-<0, P1A0[2,1], P1A0[3,1], P1A0[4,1]>.Transpose(e1)/P1A0[1,1];

$$L1 := \begin{bmatrix} 1 & 0 & 0 & 0 \\ \frac{1}{4} & 1 & 0 & 0 \\ \frac{1}{2} & 0 & 1 & 0 \\ \frac{1}{3} & 0 & 0 & 1 \end{bmatrix}$$

Primo passo del metodo di Gauss

> A1 := L1.P1A0;

$$A1 := \begin{bmatrix} 12 & -24 & -36 & -48 \\ 0 & -4 & 2 & 36 \\ 0 & 12 & -24 & -36 \\ 0 & -6 & 24 & -6 \end{bmatrix}$$

Matrice di scambio seconda e terza riga

> P2 := <e1|e3|e2|e4>;

$$P2 := \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Scambio la seconda con la terza riga

```
> P2A1 := P2.A1;
```

$$P2A1 := \begin{bmatrix} 12 & -24 & -36 & -48 \\ 0 & 12 & -24 & -36 \\ 0 & -4 & 2 & 36 \\ 0 & -6 & 24 & -6 \end{bmatrix}$$

Matrice di eliminazione

```
> L2 := ID-<0,0,P2A1[3,2],P2A1[4,2]>.Transpose(e2)/P2A1[2,2];
```

$$L2 := \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & \frac{1}{3} & 1 & 0 \\ 0 & \frac{1}{2} & 0 & 1 \end{bmatrix}$$

Secondo Passo del metodo di Gauss

```
> A2 := L2.P2A1;
```

$$A2 := \begin{bmatrix} 12 & -24 & -36 & -48 \\ 0 & 12 & -24 & -36 \\ 0 & 0 & -6 & 24 \\ 0 & 0 & 12 & -24 \end{bmatrix}$$

Matrice di scambio terza e quarta riga

```
> P3 := <e1|e2|e4|e3>;
```

$$P3 := \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Scambia terza e quarta riga

```
> P3A2 := P3.A2;
```

$$P3A2 := \begin{bmatrix} 12 & -24 & -36 & -48 \\ 0 & 12 & -24 & -36 \\ 0 & 0 & 12 & -24 \\ 0 & 0 & -6 & 24 \end{bmatrix}$$

Matrice di eliminazione

> L3 := ID-<0,0,0,P3A2[4,3]>.Transpose(e3)/P3A2[3,3];

$$L3 := \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & \frac{1}{2} & 1 \end{bmatrix}$$

Terzo passo del metodo di Gauss

> A3 := L3.P3A2;

$$A3 := \begin{bmatrix} 12 & -24 & -36 & -48 \\ 0 & 12 & -24 & -36 \\ 0 & 0 & 12 & -24 \\ 0 & 0 & 0 & 12 \end{bmatrix}$$

Matrici P, L, U

> P := P3.P2.P1:

L := P.(L3.P3.L2.P2.L1.P1)^(-1):

U := A3:

P, L, U ;

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 & 0 \\ -\frac{1}{2} & 1 & 0 & 0 \\ -\frac{1}{3} & -\frac{1}{2} & 1 & 0 \\ -\frac{1}{4} & -\frac{1}{3} & -\frac{1}{2} & 1 \end{bmatrix}, \begin{bmatrix} 12 & -24 & -36 & -48 \\ 0 & 12 & -24 & -36 \\ 0 & 0 & 12 & -24 \\ 0 & 0 & 0 & 12 \end{bmatrix}$$

Controllo

> R := P.A - L.U;

$$R := \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Calcolo la soluzione del primo problema

```
> b := < 10, -48, 12, 34>:
Pb := P.b:
z := L^(-1).Pb:
x := U^(-1).z:
b, Pb, z, x ;
```

$$\begin{bmatrix} 10 \\ -48 \\ 12 \\ 34 \end{bmatrix}, \begin{bmatrix} -48 \\ 12 \\ 34 \\ 10 \end{bmatrix}, \begin{bmatrix} -48 \\ -12 \\ 12 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

Calcolo la soluzione del secondo problema

```
> b := < 168, -240, -24, 104>:
Pb := P.b:
z := L^(-1).Pb:
x := U^(-1).z:
b, Pb, z, x ;
```

$$\begin{bmatrix} 168 \\ -240 \\ -24 \\ 104 \end{bmatrix}, \begin{bmatrix} -240 \\ -24 \\ 104 \\ 168 \end{bmatrix}, \begin{bmatrix} -240 \\ -144 \\ -48 \\ 36 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix}$$

## Esercizio 2

libero la variabile x dell'esercizio precedente

```
> x := 'x';
```

x := x

Funzione di partenza

```
> f := x -> x - 1/(1+x^2);
```

$$f := x \rightarrow x - \frac{1}{1+x^2}$$

Derivata prima

```
> df := D(f);
```

$$df := x \rightarrow 1 + \frac{2x}{(1+x^2)^2}$$

Metodo di Newton

```
> Newton := unapply( factor(x - f(x) / df(x)), x);
```

$$\text{Newton} := x \rightarrow \frac{3x^2 + 1}{1 + 2x^2 + x^4 + 2x}$$

Metodo delle secanti

```
> Secanti := unapply( factor( (y*f(x)-x*f(y)) / (f(x)-f(y))), x, y);
```

$$\text{Secanti} := (x, y) \rightarrow \frac{x^2 + yx + 1 + y^2}{x^2 + x^2y^2 + x + 1 + y^2 + y}$$

Metodo di Newton a partire da  $x_0 = 1$ :

```
> x0 := 1:
x1 := Newton(x0):
x2 := Newton(x1):
x3 := Newton(x2):
x4 := Newton(x3):
<x0, x1, x2, x3, x4>,
evalf(<x0, x1, x2, x3, x4>) ;
```

$$\begin{bmatrix} 1 \\ \frac{2}{3} \\ \frac{189}{277} \\ \frac{7054924634}{10339494587} \\ \frac{27391347543685458748085029693768512086653}{40143970962363781787578928260040051883429} \end{bmatrix}, \begin{bmatrix} 1. \\ 0.66666666667 \\ 0.6823104693 \\ 0.6823278038 \\ 0.6823278038 \end{bmatrix}$$

Metodo delle secanti a partire da  $x_0 = 1$   $x_1 = 2$  ;

```
> x0 := 1:
x1 := 2:
x2 := Secanti(x0, x1):
x3 := Secanti(x1, x2):
x4 := Secanti(x2, x3):
<x0, x1, x2, x3, x4>,
evalf(<x0, x1, x2, x3, x4>) ;
```

$$\begin{bmatrix} 1 \\ 2 \\ \frac{8}{13} \\ \frac{1117}{1607} \\ \frac{999252034}{1464355061} \end{bmatrix}, \begin{bmatrix} 1. \\ 2. \\ 0.6153846154 \\ 0.6950840075 \\ 0.6823837064 \end{bmatrix}$$

### Esercizio 3

Punti di interpolazione:

```
> X := [0, 1, 2, -1, -2];
   Y := [1, 3, 7, 1, 3];
```

```
X := [0, 1, 2, -1, -2]
Y := [1, 3, 7, 1, 3]
```

Polinomio interpolante:

```
> interp( X, Y, 'z');
```

$$z^2 + z + 1$$

Costruzione delle differenze divise di ordine 0

```
> f1 := Y[1];
   f2 := Y[2];
   f3 := Y[3];
   f4 := Y[4];
   f5 := Y[5];
```

```
f1 := 1
f2 := 3
f3 := 7
f4 := 1
f5 := 3
```

Differenze divise

```
> f12 := (f2-f1) / (X[2]-X[1]);
   f23 := (f3-f2) / (X[3]-X[2]);
   f34 := (f4-f3) / (X[4]-X[3]);
   f45 := (f5-f4) / (X[5]-X[4]);
```

```
f12 := 2
f23 := 4
f34 := 2
f45 := -2
```

### Differenze divise seconde

```
> f123 := (f23-f12)/(X[3]-X[1]);  
f234 := (f34-f23)/(X[4]-X[2]);  
f345 := (f45-f34)/(X[5]-X[3]);  
f123 := 1  
f234 := 1  
f345 := 1
```

### Differenze divise terze

```
> f1234 := (f234-f123)/(X[4]-X[1]);  
f2345 := (f345-f234)/(X[5]-X[2]);  
f1234 := 0  
f2345 := 0
```

### Differenze divise quarte

```
> f12345 := (f2345-f1234)/(X[5]-X[1]);  
f12345 := 0
```

### Polinomi della base

```
> w0 := 1 ;  
w1 := x-X[1] ;  
w2 := expand(w1 * ( x - X[2])) ;  
w3 := expand(w2 * ( x - X[3])) ;  
w4 := expand(w3 * ( x - X[4])) ;  
w0 := 1  
w1 := x  
w2 := x2 - x  
w3 := x3 - 3 x2 + 2 x  
w4 := x4 - 2 x3 - x2 + 2 x
```

### Polinomio interpolante

```
> p := f1*w0 + f12 * w1 + f123 * w2 + f1234 * w3 + f12345 * w4 ;  
p := x2 + x + 1
```

## Esercizio 4

### Funzione da integrare:

```
> f := x -> (1+x^2)*cos(2*x) ;  
f := x → (1 + x2) cos(2 x)
```

### Integrale esatto

```
> a,b := -1,2:  
int(f(x),x=a..b);  
esatto := evalf(%);
```



$$\frac{3}{4} \sin(2) + \frac{1}{2} \cos(2) + \frac{9}{4} \sin(4) + \cos(4)$$

esatto := -1.882549583

Derivata seconda della funzione

```
> ddf := (D@D)(f) ;  
collect(ddf(x), cos(2*x)) ;
```

$$\text{ddf} := x \rightarrow 2 \cos(2x) - 8x \sin(2x) - 4(1+x^2) \cos(2x)$$

$$(-2 - 4x^2) \cos(2x) - 8x \sin(2x)$$

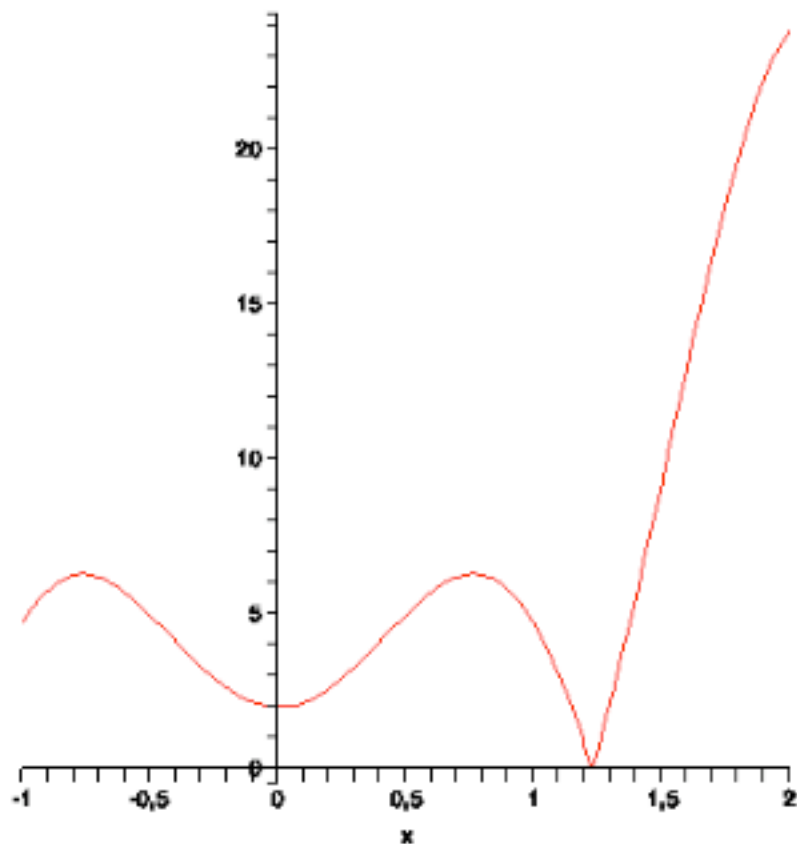
Possibile costante che maggiore il modulo della derivata seconda

```
> M := 2 + 16 + 4*(1+4) ;
```

M := 38

Verifica grafica:

```
> plot(abs(ddf(x)), x=a..b) ;
```



Calcolo in numero minimo stimato di intervalli

```
> err := 10^(-5) = (b-a)^3 / (12*n^2) * M ;
```

$$\text{err} := \frac{1}{100000} = \frac{171}{2n^2}$$

```
> isolate(err,n^2) ;
```

$$n^2 = 8550000$$

```
> evalf(sqrt(rhs(%)));
```

$$2924.038304$$

Intervalli stimati: 2925

```
> h := (b-a)/6 ;
```

$$h := \frac{1}{2}$$

```
> trap := evalf(h*(f(a)+f(b))/2+h*sum(f(a+h*i),i=1..5)) ;
```

$$\text{trap} := -1.874634706$$

```
> trap - esatto ;
```

$$0.007914877$$

## - Esercizio 5

```
> h := 'h';
```

$$h := h$$

Funzione da integrare

```
> f := (x,y) -> x^2 - 3*y ;
```

$$f := (x, y) \rightarrow x^2 - 3y$$

Derivata prima

```
> dy := f(x,y) ;
```

$$dy := x^2 - 3y$$

Derivata seconda

```
> ddy := diff(dy,x)+diff(dy,y)*f(x,y) ;
```

$$\text{ddy} := 2x - 3x^2 + 9y$$

Derivata terza

```
> dddy := diff(ddy,x)+diff(ddy,y)*f(x,y) ;
```

$$\text{dddy} := 2 - 6x + 9x^2 - 27y$$

Costruzione della serie di Taylor troncata

```
> ynew := unapply(y+dy*h+ddy*h^2/2+dddy*h^3/6, x, y, h) ;
```

$$y_{\text{new}} := (x, y, h) \rightarrow y + (x^2 - 3y)h + \frac{1}{2}(2x - 3x^2 + 9y)h^2 + \frac{1}{6}(2 - 6x + 9x^2 - 27y)h^3$$

Calcolo alcuni passi

```
> x0, y0 := 1, 2;
```

$$x_0, y_0 := 1, 2$$

```
> h := 0.2 ;
```

```
h := 0.2
```

```
> x1 := x0 + h ;  
y1 := ynew(x0, y0, h) ;
```

```
x1 := 1.2  
y1 := 1.274666667
```

```
> x2 := x1 + h ;  
y2 := ynew(x1, y1, h) ;
```

```
x2 := 1.4  
y2 := 0.9533653334
```

```
> x3 := x2 + h ;  
y3 := ynew(x2, y2, h) ;
```

```
x3 := 1.6  
y3 := 0.8640174081
```

## - Esercizio 6

Definizione del problema

```
> p := x -> x-1 ;  
q := x -> -1 ;  
r := x -> x^2 - 2 * x ;  
xa, ya := -1, 1 ;  
xb, yb := 3, 13 ;
```

```
p := x → x - 1  
q := x → -1  
r := x → x2 - 2 x  
xa, ya := -1, 1  
xb, yb := 3, 13
```

Differenze finite:

```
> n := 4 ;  
h := (xb-xa) / n ;  
x[0] := xa ;  
x[1] := xa + h ;  
x[2] := xa + 2*h ;  
x[3] := xa + 3*h ;  
x[4] := xa + 4*h ;
```

```
n := 4  
h := 1  
x0 := -1  
x1 := 0  
x2 := 1  
x3 := 2
```

$$x_4 := 3$$

```
> eq := k -> (y[k+1]-2*y[k]+y[k-1])/h^2 +  
p(x[k]) * (y[k+1]-y[k-1])/(2*h) +  
q(x[k]) * y[k] - r(x[k]) ;
```

$$\text{eq} := k \rightarrow \frac{y_{1+k} - 2y_k + y_{k-1}}{h^2} + \frac{p(x_k)(y_{1+k} - y_{k-1})}{2h} + q(x_k)y_k - r(x_k)$$

Equazioni risultanti

```
> eq1 := eq(1) ;  
eq2 := eq(2) ;  
eq3 := eq(3) ;
```

$$\text{eq1} := \frac{1}{2}y_2 - 3y_1 + \frac{3}{2}y_0$$

$$\text{eq2} := y_3 - 3y_2 + y_1 + 1$$

$$\text{eq3} := \frac{3}{2}y_4 - 3y_3 + \frac{1}{2}y_2$$

Estraggo il sistema lineare dalle equazioni

```
> A := linalg[genmatrix]([eq1,eq2,eq3],[y[1],y[2],y[3]],'b') :  
A := convert(A,Matrix);
```

$$A := \begin{bmatrix} -3 & \frac{1}{2} & 0 \\ 1 & -3 & 1 \\ 0 & \frac{1}{2} & -3 \end{bmatrix}$$

```
> b := Transpose(convert(b,Vector));
```

$$b := \begin{bmatrix} -\frac{3}{2}y_0 \\ -1 \\ -\frac{3}{2}y_4 \end{bmatrix}$$

Sostituisco le condizioni al contorno

```
> b := subs(y[0]=ya, y[4]=yb, b) ;
```

$$b := \begin{bmatrix} -\frac{3}{2} \\ -1 \\ -\frac{39}{2} \end{bmatrix}$$

Risolvo il sistema lineare

```
> LinearSolve(A,b) ;
```

$$\begin{bmatrix} 1 \\ 3 \\ 7 \end{bmatrix}$$

## Esercizio 7

Funzione da integrare

```
> f := x -> 1 + x^2;
```

$$f := x \rightarrow 1 + x^2$$

Estremi di integrazione

```
> a,b := -1,3 ;
```

$$a, b := -1, 3$$

Integrale esatto

```
> int(f(x),x=a..b);  
evalf(%);
```

$$\frac{40}{3}$$

$$13.33333333$$

Nodi e pesi

```
> X := [-0.7746, 0, 0.7746];  
W := [0.5555, 0.8888, 0.5555];
```

$$X := [-.7746, 0, 0.7746]$$

$$W := [0.5555, 0.8888, 0.5555]$$

```
> c := 1 ;
```

$$c := 1$$

Integrale approssimato nel primo intervallo [a,c]

Trasformazione dei nodi

```
> XT := [seq((a+c)/2+X[i]*(c-a)/2,i=1..3)];
```

$$XT := [-.7746000000, 0, 0.7746000000]$$

```
> int1 := ((c-a)/2)*sum(W[i]*f(XT[i]),i=1..3);
```

$$int1 := 2.666405732$$

Integrale approssimato nel primo intervallo [c,b]

Trasformazione dei nodi

```
> XT := [seq((c+b)/2+X[i]*(b-c)/2,i=1..3)];
```

$$XT := [1.225400000, 2, 2.774600000]$$

```
> int2 := ((b-c)/2)*sum(W[i]*f(XT[i]),i=1..3) ;  
int2 := 10.66560573
```

Risultato finale

```
> int1+int2 ;  
13.33201146
```

## Esercizio 8

Matrice del sistema

```
> L := <<0,0,-1>|<0,0,-1>|<0,0,0>>;  
DG := <<2,0,0>|<0,4,0>|<0,0,2>>;  
U := <<0,0,0>|<-1,0,0>|<-1,-1,0>>;  
A := DG+L+U ;
```

$$L := \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ -1 & -1 & 0 \end{bmatrix}$$

$$DG := \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$U := \begin{bmatrix} 0 & -1 & -1 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$A := \begin{bmatrix} 2 & -1 & -1 \\ 0 & 4 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

Termine noto

```
> b := <1,-1,1>;
```

$$b := \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

libera x, y, z

```
> x := 'x' ;  
y := 'y' ;  
z := 'z' ;
```

x:= x

y:= y

`z := z`

Metodo Iterativo

```
> iter := (DG+L) .<x[k+1],y[k+1],z[k+1]> + U.<x[k],y[k],z[k]> - b ;
```

$$\text{iter} := \begin{bmatrix} 2x_{k+1} - y_k - z_k - 1 \\ 4y_{k+1} - z_k + 1 \\ -x_{k+1} - y_{k+1} + 2z_{k+1} - 1 \end{bmatrix}$$

```
> isolate(iter[1]=0,x[k+1]);  
> isolate(iter[2]=0,y[k+1]);  
> isolate(iter[3]=0,z[k+1]);
```

$$x_{k+1} = \frac{1}{2}y_k + \frac{1}{2}z_k + \frac{1}{2}$$

$$y_{k+1} = \frac{1}{4}z_k - \frac{1}{4}$$

$$z_{k+1} = \frac{1}{2}x_{k+1} + \frac{1}{2}y_{k+1} + \frac{1}{2}$$

Matrice di iterazione  $-(D+L)^{-1}U$

```
> MI := -(DG+L)^(-1).U;
```

$$\text{MI} := \begin{bmatrix} 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 0 & \frac{1}{4} \\ 0 & \frac{1}{4} & \frac{3}{8} \end{bmatrix}$$

Polinomio caratteristico della matrice di iterazione

```
> chpoly := CharacteristicPolynomial(MI, z);
```

$$\text{chpoly} := z^3 - \frac{3}{8}z^2 - \frac{1}{16}z$$

```
> res := solve(chpoly, z);
```

$$\text{res} := 0, \frac{1}{2}, \frac{-1}{8}$$

Calcolo il raggio spettrale

```
> seq(abs(res[i]), i=1..3);
```

$$0, \frac{1}{2}, \frac{1}{8}$$

Raggio spettrale =  $1/2 < 1 \implies$  il metodo converge.

Faccio alcune iterate:

```
> P0 := <2,1,2> ;
```

$$P0 := \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}$$

```
> P1 := (DG+L)^(-1).(b-U.P0) :  
P1, evalf(P1) ;
```

$$\begin{bmatrix} 2 \\ \frac{1}{4} \\ \frac{13}{8} \end{bmatrix}, \begin{bmatrix} 2. \\ 0.2500000000 \\ 1.6250000000 \end{bmatrix}$$

```
> P2 := (DG+L)^(-1).(b-U.P1) :  
P2, evalf(P2) ;
```

$$\begin{bmatrix} \frac{23}{16} \\ \frac{5}{32} \\ \frac{83}{64} \end{bmatrix}, \begin{bmatrix} 1.437500000 \\ 0.1562500000 \\ 1.296875000 \end{bmatrix}$$

Calcolo i residui

```
> R1 := b - A . P1 :  
R2 := b - A . P2 :  
R1, evalf(R1) ;  
R2, evalf(R2) ;
```

$$\begin{bmatrix} -\frac{9}{8} \\ -\frac{3}{8} \\ 0 \end{bmatrix}, \begin{bmatrix} -1.125000000 \\ -0.3750000000 \\ 0. \end{bmatrix}$$

$$\begin{bmatrix} -\frac{27}{64} \\ -\frac{21}{64} \\ 0 \end{bmatrix}, \begin{bmatrix} -0.4218750000 \\ -0.3281250000 \\ 0. \end{bmatrix}$$



### Norma infinito

```
> max(seq(abs(R1[i]), i=1..3));  
max(seq(abs(R2[i]), i=1..3));  
evalf(%), evalf(%);
```

$$\frac{9}{8}$$

$$\frac{27}{64}$$

1.125000000, 0.4218750000

### Norma 1

```
> add(abs(R1[i]), i=1..3);  
add(abs(R2[i]), i=1..3);  
evalf(%), evalf(%);
```

$$\frac{3}{2}$$

$$\frac{3}{4}$$

1.500000000, 0.7500000000

### Norma 2

```
> sqrt(add(abs(R1[i])^2, i=1..3));  
sqrt(add(abs(R2[i])^2, i=1..3));  
evalf(%), evalf(%);
```

$$\frac{3}{8}\sqrt{10}$$

$$\frac{3}{64}\sqrt{130}$$

1.185854122, 0.5344572305

## Esercizio 9

### Tabella dei punti

```
> X := [-2, -2, -1, 0, 2, 1, 3, -3, 2, 5];  
Y := [-1, -1, 0, 1, 3, 2, 4, -2, 3, 6];
```

X := [-2, -2, -1, 0, 2, 1, 3, -3, 2, 5]

Y := [-1, -1, 0, 1, 3, 2, 4, -2, 3, 6]

```
> n := nops(X);
```

n := 10

```
> SX := add(X[i], i=1..n);  
SX2 := add(X[i]^2, i=1..n);  
SX3 := add(X[i]^3, i=1..n);  
SX4 := add(X[i]^4, i=1..n);  
SY := add(Y[i], i=1..n);  
SXY := add(X[i]*Y[i], i=1..n);
```

```

SX2Y := add(X[i]^2*Y[i],i=1..n) ;
      SX := 5
      SX2 := 61
      SX3 := 125
      SX4 := 853
      SY := 15
      SXY := 66
      SX2Y := 186

```

```

> A := <<n, SX, SX2>|<SX, SX2, SX3>|<SX2, SX3, SX4>>;

```

$$A := \begin{bmatrix} 10 & 5 & 61 \\ 5 & 61 & 125 \\ 61 & 125 & 853 \end{bmatrix}$$

```

> b := <SY, SXY, SX2Y> ;

```

$$b := \begin{bmatrix} 15 \\ 66 \\ 186 \end{bmatrix}$$

```

> res := A^(-1).b ;

```

$$\text{res} := \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Soluzione

```

> x := 'x' :
  p := 'p' :

```

```

> p := res[1]+ x * res[2] + x^2 * res[3] ;
      p := 1 + x

```