

# > Soluzioni del compito di Calcolo Numerico del 25 ottobre 2004

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## [-] **Esercizio 1**

```
> restart:  
with(LinearAlgebra) :  
with(plots):  
with(Student[Calculus1]):
```

Warning, the name changecoords has been redefined

Primitiva della funzione da integrare

```
> F := cos(x^2) ;
```

$$F := \cos(x^2)$$

Funzione da integrare

```
> f := expand(diff(F,x)) ;
```

$$f := -2 \sin(x^2) x$$

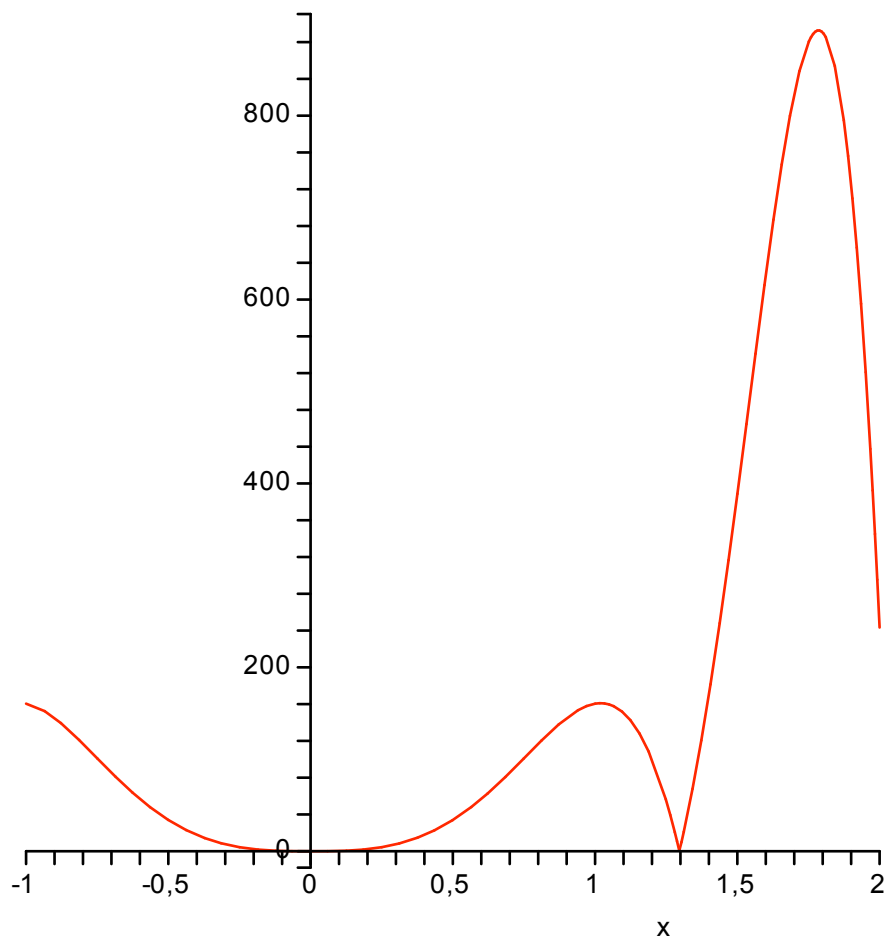
Derivata quarta

```
> ddddf := expand(diff(f,x,x,x,x)) ;
```

$$ddddf := -32 \sin(x^2) x^5 + 160 \cos(x^2) x^3 + 120 \sin(x^2) x$$

Studio della derivata quarta

```
> plot( abs(ddddf), x=-1..2 ) ;
```



stima del modulo della derivata quarta

```
> M := 32*2^5+160*2^3+120*2;
```

```
M := 2544
```

stima degli intervalli necessari col metodo di Simpson per avere  $E < 0.001$

```
> a,b,E := -1,2,0.001 ;
```

```
expr := E - (b-a)^5/(180*n^4)*M ;
```

```
a, b, E := -1, 2, 0.001
```

```
expr := 0.001 -  $\frac{17172}{5 n^4}$ 
```

```
> expr1 := isolate( expr, n^4 ) ;
```

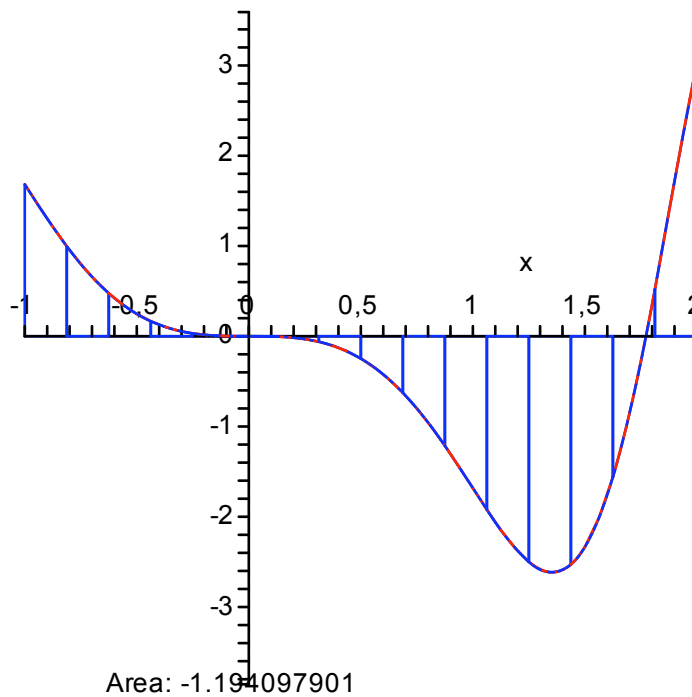
```
expr1 :=  $n^4 = 3.434400000 \cdot 10^6$ 
```

```
> nint := (op(2,expr1))^(1/4) ;
```

```
nint := 43.04896544
```

```
> ApproximateInt(f, x=-1..2, method = simpson, partition = 16, output = plot);
```

An Approximation of the Integral of  
 $f(x) = -2 \cdot \sin(x^2) \cdot x$   
on the Interval  $[-1, 2]$   
Using Simpson's Rule  
Approximate Value: -1.193945927



— f(x)

```
> evalf(ApproximateInt(f, x=-1..2, method = simpson, partition = 6));
-1.202497505
> esatto := evalf(subs(x=2,F)-subs(x=-1,F)) ;
esatto := -1.193945927
```

## Esercizio 2

```
> restart;
with(LinearAlgebra) :
```

Soluzione del problema di interpolazione

```
> psol := x -> 3*x-x^3;
```

$psol := x \rightarrow 3x - x^3$

Punti di interpolazione:

```
> X := [-2,0,1,2,5];
Y := [seq(psol(X[i]),i=1..5)];
```

$X := [-2, 0, 1, 2, 5]$

$Y := [2, 0, 2, -2, -110]$

Polinomio interpolante:

```
> interp( X, Y, 'z');
```

$$-z^3 + 3z$$

Costruzione delle differenze divise di ordine 0

```
> f1 := Y[1];  
f2 := Y[2];  
f3 := Y[3];  
f4 := Y[4];  
f5 := Y[5];
```

$$f1 := 2$$

$$f2 := 0$$

$$f3 := 2$$

$$f4 := -2$$

$$f5 := -110$$

Differenze divise

```
> f12 := (f2-f1)/(X[2]-X[1]);  
f23 := (f3-f2)/(X[3]-X[2]);  
f34 := (f4-f3)/(X[4]-X[3]);  
f45 := (f5-f4)/(X[5]-X[4]);
```

$$f12 := -1$$

$$f23 := 2$$

$$f34 := -4$$

$$f45 := -36$$

Differenze divise seconde

```
> f123 := (f23-f12)/(X[3]-X[1]);  
f234 := (f34-f23)/(X[4]-X[2]);  
f345 := (f45-f34)/(X[5]-X[3]);
```

$$f123 := 1$$

$$f234 := -3$$

$$f345 := -8$$

Differenze divise terze

```
> f1234 := (f234-f123)/(X[4]-X[1]);  
f2345 := (f345-f234)/(X[5]-X[2]);
```

$$f1234 := -1$$

$$f2345 := -1$$

Differenze divise quarte

```
> f12345 := (f2345-f1234)/(X[5]-X[1]);
```

$$f12345 := 0$$

Polinomi della base

```
> w0 := 1 ;
```

```

w1 := x-X[1] ;
w2 := expand(w1 * ( x - X[2])) ;
w3 := expand(w2 * ( x - X[3])) ;
w4 := expand(w3 * ( x - X[4])) ;

w0 := 1
w1 := x + 2
w2 := x2 + 2x
w3 := x3 + x2 - 2x
w4 := x4 - x3 - 4x2 + 4x

```

Polinomio interpolante

```

> p := f1*w0 + f12 * w1 + f123 * w2 + f1234 * w3 + f12345 * w4 ;
p := 3x - x3

```

## [-] Esercizio 3

```

> restart:
with(LinearAlgebra) :

```

Definizione del problema

```

> p := x -> 1-x2 ;
q := x -> -1 ;
r := x -> x - 4 ;
xa, xb := -2, 2 ;
ya, yb := 0, 14 ;

```

```

p := x -> 1 - x2
q := x -> -1
r := x -> x - 4
xa, xb := -2, 2
ya, yb := 0, 14

```

Differenze finite:

```

> n := 4 ;
h := (xb-xa) / n ;
x[0] := xa ;
x[1] := xa + h ;
x[2] := xa + 2*h ;
x[3] := xa + 3*h ;
x[4] := xa + 4*h ;

```

```

n := 4
h := 1
x0 := -2
x1 := -1
x2 := 0

```

$$x_3 := 1$$

$$x_4 := 2$$

```
> eq := k -> (y[k+1]-2*y[k]+y[k-1])/h^2 +  
p(x[k]) * (y[k+1]-y[k-1])/(2*h) +  
q(x[k]) * y[k] - r(x[k]) ;
```

$$eq := k \rightarrow \frac{y_{k+1} - 2y_k + y_{k-1}}{h^2} + \frac{p(x_k)(y_{k+1} - y_{k-1})}{2h} + q(x_k)y_k - r(x_k)$$

Equazioni risultanti

```
> eq1 := eq(1) ;  
eq2 := eq(2) ;  
eq3 := eq(3) ;
```

$$eq1 := y_2 - 3y_1 + y_0 + 5$$

$$eq2 := \frac{3}{2}y_3 - 3y_2 + \frac{1}{2}y_1 + 4$$

$$eq3 := y_4 - 3y_3 + y_2 + 3$$

Estraggo il sistema lineare dalle equazioni

```
> A := linalg[genmatrix]([eq1,eq2,eq3],[y[1],y[2],y[3]], 'b') :  
A := convert(A,Matrix);
```

$$A := \begin{bmatrix} -3 & 1 & 0 \\ \frac{1}{2} & -3 & \frac{3}{2} \\ 0 & 1 & -3 \end{bmatrix}$$

```
> b := Transpose(convert(b,Vector));
```

$$b := \begin{bmatrix} -y_0 - 5 \\ -4 \\ -y_4 - 3 \end{bmatrix}$$

Sostituisco le condizioni al contorno

```
> b := subs(y[0]=ya, y[4]=yb, b) ;
```

$$b := \begin{bmatrix} -5 \\ -4 \\ -17 \end{bmatrix}$$

Risolvo il sistema lineare

```
> res := LinearSolve(A,b) ;  
evalf(res) ;
```

$$res := \begin{bmatrix} \frac{25}{7} \\ \frac{40}{7} \\ \frac{53}{7} \end{bmatrix}$$

$$\begin{bmatrix} 3.571428571 \\ 5.714285714 \\ 7.571428571 \end{bmatrix}$$

## [-] Esercizio 4

```
> restart;
```

```
> # Punti di interpolazione
```

```
> sol := x -> x^3-x ;
```

$$sol := x \rightarrow x^3 - x$$

```
> X0,X1,X2,X3,X4 := -1,0,1,2,3 ;
```

```
Y0,Y1,Y2,Y3,Y4 := sol(X0),sol(X1),sol(X2),sol(X3),sol(X4) ;
```

```
X0,X1,X2,X3,X4 := -1,0,1,2,3
```

```
Y0,Y1,Y2,Y3,Y4 := 0,0,0,6,24
```

```
> # condizioni al contorno
```

```
S2_init := (D@@2)(sol)(X0) ;
```

```
S2_final := 24 ; # (D@@2)(sol)(X4) ;
```

```
S2_init := -6
```

```
S2_final := 24
```

```
> # Equazioni dei momenti
```

```
# notate che h[k] = 1 costante perche i punti sono
```

```
# equispaziati
```

```
EQ1 := M0*(1/2) + 2*M1 + M2*(1/2) = 3*((Y2-Y1)-(Y1-Y0)) ;
```

```
EQ2 := M1*(1/2) + 2*M2 + M3*(1/2) = 3*((Y3-Y2)-(Y2-Y1)) ;
```

```
EQ3 := M2*(1/2) + 2*M3 + M4*(1/2) = 3*((Y4-Y3)-(Y3-Y2)) ;
```

```
EQINIT := M0 = S2_init ;
```

```
EQFINAL := M4 = S2_final ;
```

$$EQ1 := \frac{1}{2} M0 + 2 M1 + \frac{1}{2} M2 = 0$$

$$EQ2 := \frac{1}{2} M1 + 2 M2 + \frac{1}{2} M3 = 18$$

$$EQ3 := \frac{1}{2} M2 + 2 M3 + \frac{1}{2} M4 = 36$$

$$EQINIT := M0 = -6$$

$$EQFINAL := M4 = 24$$

```
> RES := solve({EQ1,EQ2,EQ3,EQINIT,EQFINAL},{M0,M1,M2,M3,M4}) ;
```

$$RES := \left\{ M0 = -6, M4 = 24, M3 = \frac{291}{28}, M1 = \frac{-3}{28}, M2 = \frac{45}{7} \right\}$$

```
> # Calcolo i tratti di cubica
```

```
S1 := Y0 + (Y1-Y0 - (M1+2*M0) / 6) * (x-X0)
      + (M0/2)*(x-X0)^2
      + ((M1-M0)/6)*(x-X0)^3 ;
```

```
expand(subs(RES,S1)) ;
```

$$S1 := \left( -\frac{1}{6} M1 - \frac{1}{3} M0 \right) (x+1) + \frac{1}{2} M0 (x+1)^2 + \frac{1}{6} (M1 - M0) (x+1)^3 \\ - \frac{29}{28} x - \frac{3}{56} x^2 + \frac{55}{56} x^3$$

```
> S2 := Y1 + (Y2-Y1 - (M2+2*M1) / 6) * (x-X1)
      + (M1/2)*(x-X1)^2
      + ((M2-M1)/6)*(x-X1)^3 ;
```

```
expand(subs(RES,S2)) ;
```

$$S2 := \left( -\frac{1}{6} M2 - \frac{1}{3} M1 \right) x + \frac{1}{2} M1 x^2 + \frac{1}{6} (M2 - M1) x^3 \\ - \frac{29}{28} x - \frac{3}{56} x^2 + \frac{61}{56} x^3$$

```
> S3 := Y2 + (Y3-Y2 - (M3+2*M2) / 6) * (x-X2)
      + (M2/2)*(x-X2)^2
      + ((M3-M2)/6)*(x-X2)^3 ;
```

```
expand(subs(RES,S3)) ;
```

$$S3 := \left( 6 - \frac{1}{6} M3 - \frac{1}{3} M2 \right) (x-1) + \frac{1}{2} M2 (x-1)^2 + \frac{1}{6} (M3 - M2) (x-1)^3 \\ - \frac{65}{28} x + \frac{3}{7} + \frac{69}{56} x^2 + \frac{37}{56} x^3$$

```
> S4 := Y3 + (Y4-Y3 - (M4+2*M3) / 6) * (x-X3)
      + (M3/2)*(x-X3)^2
      + ((M4-M3)/6)*(x-X3)^3 ;
```

```
expand(subs(RES,S4)) ;
```

$$S4 := 6 + \left( 18 - \frac{1}{6} M4 - \frac{1}{3} M3 \right) (x-2) + \frac{1}{2} M3 (x-2)^2 + \frac{1}{6} (M4 - M3) (x-2)^3 \\ - \frac{87}{7} + \frac{475}{28} x - \frac{471}{56} x^2 + \frac{127}{56} x^3$$

```
>
```

```
>
```



