

Example of a function constrained to a circle solved using Lagrange Multiplier

```
> restart;
```

```
> f := (x,y) -> x+y ;
```

$$f := (x, y) \rightarrow x + y \quad (1)$$

```
> h := (x,y) -> 1-x^2-y^2 ;
```

$$h := (x, y) \rightarrow 1 - x^2 - y^2 \quad (2)$$

Build the non linear system of the Lagrange multiplier

```
> gradf := [ diff(f(x,y),x), diff(f(x,y),y) ] ;
```

$$\text{gradf} := [1, 1] \quad (3)$$

```
> gradh := [ diff(h(x,y),x), diff(h(x,y),y) ] ;
```

$$\text{gradh} := [-2x, -2y] \quad (4)$$

```
> EQ1 := gradf[1] - lambda * gradh[1] = 0 ;
```

```
> EQ2 := gradf[2] - lambda * gradh[2] = 0 ;
```

```
> EQ3 := h(x,y) = 0 ;
```

$$\begin{aligned} \text{EQ1} &:= 1 + 2\lambda x = 0 \\ \text{EQ2} &:= 1 + 2\lambda y = 0 \\ \text{EQ3} &:= 1 - x^2 - y^2 = 0 \end{aligned} \quad (5)$$

```
> #solve({EQ1,EQ2,EQ3},{x,y,lambda}) ; allvalues(%);
```

Solve the nonlinear system step by step

```
> SOLx := solve(EQ1, {x}) ;
```

```
> SOLy := solve(EQ2, {y}) ;
```

$$\begin{aligned} \text{SOLx} &:= \left\{ x = -\frac{1}{2\lambda} \right\} \\ \text{SOLy} &:= \left\{ y = -\frac{1}{2\lambda} \right\} \end{aligned} \quad (6)$$

```
> EQlambda := subs(SOLy, subs(SOLx, EQ3)) ;
```

$$\text{EQlambda} := 1 - \frac{1}{2\lambda^2} = 0 \quad (7)$$

```
> SOLlamda := solve(EQlambda, {lambda}) ;
```

$$\text{SOLlamda} := \left\{ \lambda = \frac{1}{2}\sqrt{2} \right\}, \left\{ \lambda = -\frac{1}{2}\sqrt{2} \right\} \quad (8)$$

The two solutions are

```
> SOL1 := op(SOLlamda[1]), op(subs(SOLlamda[1], [op(SOLx), op(SOLy)])) ;
```

```
> SOL2 := op(SOLlamda[2]), op(subs(SOLlamda[2], [op(SOLx), op(SOLy)])) ;
```

$$\text{SOL1} := \lambda = \frac{1}{2}\sqrt{2}, x = -\frac{1}{2}\sqrt{2}, y = -\frac{1}{2}\sqrt{2}$$

(9)

$$SOL2 := \lambda = -\frac{1}{2}\sqrt{2}, x = \frac{1}{2}\sqrt{2}, y = \frac{1}{2}\sqrt{2} \quad (9)$$

Check the solution

```
> subs(SOL1, [EQ1, EQ2, EQ3]) ;
subs(SOL2, [EQ1, EQ2, EQ3]) ;
```

$$\begin{aligned} & [0 = 0, 0 = 0, 0 = 0] \\ & [0 = 0, 0 = 0, 0 = 0] \end{aligned} \quad (10)$$

Find the space of vectors that are in the kernel of the constraint h(x,y)

```
> with(LinearAlgebra) :
> subs(SOL1, NullSpace(gradh)) ;
```

$$\left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\} \quad (11)$$

```
> subs(SOL1, gradh[1]*alpha + gradh[2]*beta) ;
```

$$\sqrt{2} \alpha + \sqrt{2} \beta \quad (12)$$

Build the hessian

```
> hessf := <<diff(f(x,y), x, x), diff(f(x,y), x, y)> | <diff(f(x,y), x, y), diff(f(x,y), y, y)>> ;
```

$$hessf := \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad (13)$$

```
> hessh := <<diff(h(x,y), x, x), diff(h(x,y), x, y)> | <diff(h(x,y), x, y), diff(h(x,y), y, y)>> ;
```

$$hessh := \begin{bmatrix} -2 & 0 \\ 0 & -2 \end{bmatrix} \quad (14)$$

```
> hessL := hessf - lambda * hessh ;
```

$$hessL := \begin{bmatrix} 2\lambda & 0 \\ 0 & 2\lambda \end{bmatrix} \quad (15)$$

Analyse the first solution

```
> hessL1 := subs(SOL1, hessL) ;
```

$$hessL1 := \begin{bmatrix} \sqrt{2} & 0 \\ 0 & \sqrt{2} \end{bmatrix} \quad (16)$$

The vector in the kernel of grad h(x,y)

```
> z := alpha*⟨1, -1⟩ ;
```

$$z := \begin{bmatrix} \alpha \\ -\alpha \end{bmatrix} \quad (17)$$

```
> Transpose(z) . hessL1 . z ;
```

$$2\sqrt{2} \alpha^2 \quad (18)$$

Analyse the second solution

```
> subs(SOL2, NullSpace(gradh)) ;
```

$$\left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\} \quad (19)$$

`> hessL2 := subs(SOL2, hessL) ;`

$$hessL2 := \begin{bmatrix} -\sqrt{2} & 0 \\ 0 & -\sqrt{2} \end{bmatrix} \quad (20)$$

The vector in the kernel of grad h(x,y)

`> z := alpha*<1,-1> ;`

$$z := \begin{bmatrix} \alpha \\ -\alpha \end{bmatrix} \quad (21)$$

`> Transpose(z) . hessL2 . z ;`

$$-2\sqrt{2}\alpha^2 \quad (22)$$