

Solution of KKT problem of 27/8/2012

```
> restart:  
> with(plots) :
```

Function to minimize

```
> f := x*y ;
```

$$f := xy$$

(1)

Constraints

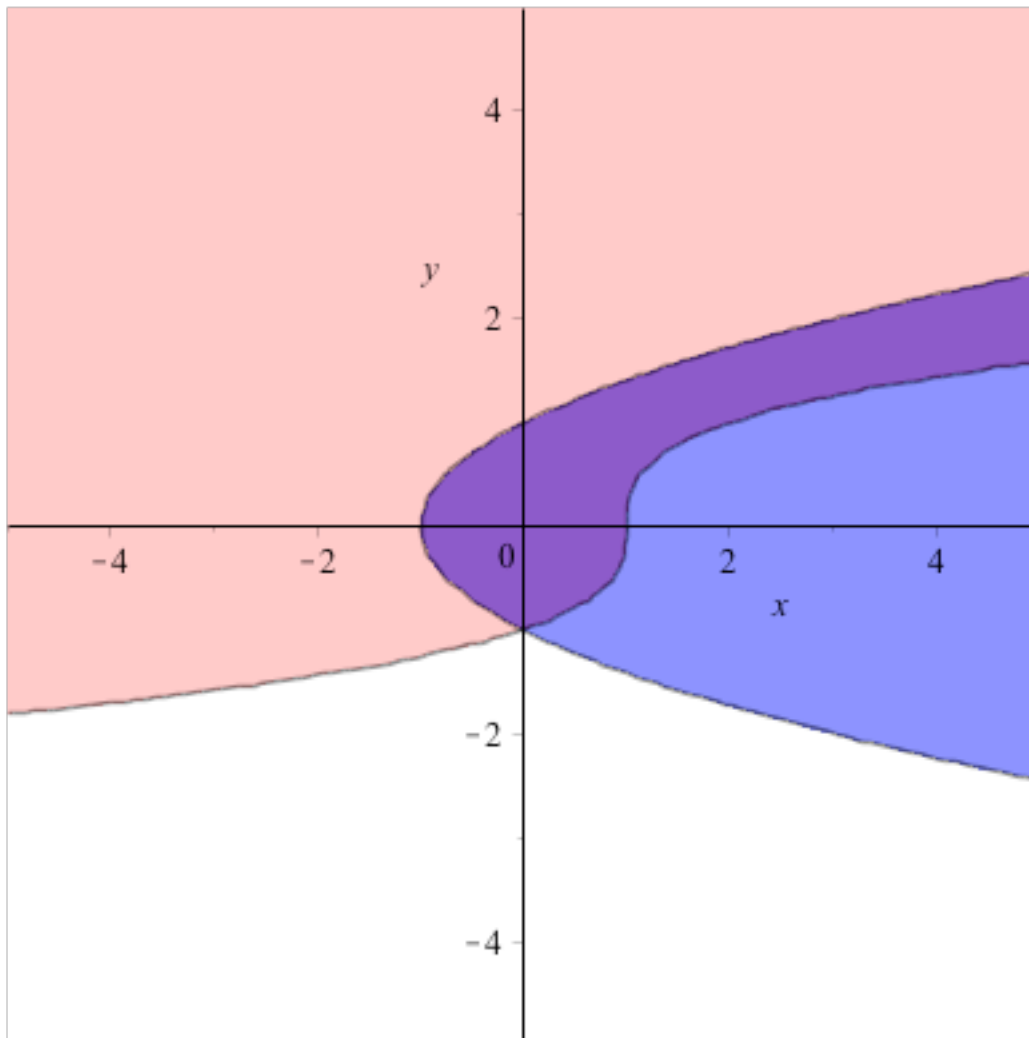
```
> g1 := x-y^2+1 ;  
g2 := y^3-x+1 ;
```

$$g1 := x - y^2 + 1$$

$$g2 := y^3 - x + 1$$

(2)

```
> A := contourplot(g1, x=-5..5, y=-5..5, coloring=["white","blue"],  
transparency=0.5, filledregions=true, contours=[0]) :  
B := contourplot(g2, x=-5..5, y=-5..5, coloring=["white","red"],  
transparency=0.5, filledregions=true, contours=[0]) :  
> display(A,B) ;
```



Define the Lagrangian

```
> L := f - mu1 * g1 - mu2 * g2 ;  
L := x y - mu1 ( x - y^2 + 1 ) - mu2 ( y^3 - x + 1 )
```

(3)

Set the KKT first order nonlinear system

```
> EQ1 := diff(L,x) ;  
EQ2 := diff(L,y) ;  
EQ3 := mu1*g1 ;  
EQ4 := mu2*g2 ;  
  
EQ1 := y - mu1 + mu2  
EQ2 := x + 2 mu1 y - 3 mu2 y^2  
EQ3 := mu1 ( x - y^2 + 1 )  
EQ4 := mu2 ( y^3 - x + 1 )
```

(4)

Try mu1=mu2=0

```
> subs(mu1=0, mu2=0, [EQ|| (1..4)] ) ;  
[y, x, 0, 0]
```

(5)

```
> SOL1 := x=0, y=0, mu1=0, mu2=0;  
SOL1 := x = 0, y = 0, mu1 = 0, mu2 = 0
```

(6)

Try mu1=0, mu2 != 0

```
> EQS := subs(mu1=0, [EQ|| (1..4)] ) ;  
EQS := [y + mu2, x - 3 mu2 y^2, 0, mu2 (y^3 - x + 1)]
```

(7)

```
> EQx := solve( EQS[4], {x} ) ; EQmu2 := solve( EQS[1], {mu2} ) ;  
subs( EQmu2, subs( EQx, EQS[2] ) ); EQy := solve( %, {y} ) ;  
EQx := {x = y^3 + 1}  
EQmu2 := {mu2 = -y  
4 y^3 + 1  
EQy := {y = -1/2 2^{1/3}}, {y = 1/4 2^{1/3} - 1/4 I sqrt(3) 2^{1/3}}, {y = 1/4 2^{1/3} + 1/4 I sqrt(3) 2^{1/3}}
```

(8)

```
> SOL2 := op(subs(EQy[1], EQx)), op(EQy[1]), mu1=0, op(subs(EQy[1], EQmu2)  
);  
SOL2 := x = 3/4, y = -1/2 2^{1/3}, mu1 = 0, mu2 = 1/2 2^{1/3}
```

(9)

Try mu2=0, mu1 != 0

```
> EQS := subs(mu2=0, [EQ|| (1..4)] ) ;  
EQS := [y - mu1, x + 2 mu1 y, mu1 (x - y^2 + 1), 0]
```

(10)

```
> EQx := solve( EQS[3], {x} ) ; EQmu1 := solve( EQS[1], {mu1} ) ;  
subs( EQmu1, subs( EQx, EQS[2] ) ); EQy := solve( %, {y} ) ;  
EQx := {x = y^2 - 1}  
EQmu1 := {mu1 = y  
3 y^2 - 1  
EQy := {y = 1/3 sqrt(3)}, {y = -1/3 sqrt(3)}
```

(11)

```
> SOL3 := op(subs(EQy[1],EQx)),op(EQy[1]),mu2=0,op(subs(EQy[1],EQmu1))
);
```

$$SOL3 := x = -\frac{2}{3}, y = \frac{1}{3}\sqrt{3}, \mu_2 = 0, \mu_1 = \frac{1}{3}\sqrt{3} \quad (12)$$

```
> SOL4 := op(subs(EQy[2],EQx)),op(EQy[2]),mu2=0,op(subs(EQy[2],EQmu1))
);
```

$$SOL4 := x = -\frac{2}{3}, y = -\frac{1}{3}\sqrt{3}, \mu_2 = 0, \mu_1 = -\frac{1}{3}\sqrt{3} \quad (13)$$

SOL4 must be discarded because $m_1 < 0$

Try $\mu_2 \neq 0, \mu_1 \neq 0$

```
> EQS := [EQ|| (1..4)] ;
```

$$EQS := [y - \mu_1 + \mu_2, x + 2\mu_1 y - 3\mu_2 y^2, \mu_1(x - y^2 + 1), \mu_2(y^3 - x + 1)] \quad (14)$$

```
> subs(solve(EQS[3],{x}),EQS[4]); SOLy := solve(%,{y});
mu2(y^3 - y^2 + 2)
```

$$SOLy := \{y = -1\}, \{y = 1 - I\}, \{y = 1 + I\} \quad (15)$$

```
> subs(SOLy[1],EQS[3]) ; SOLx := x = 0 ;
```

$$\mu_1 x$$

$$SOLx := x = 0 \quad (16)$$

```
> SYSMU := subs(SOLy[1],subs(SOLx,EQS[1..2])) ;
```

$$SYSMU := [-1 - \mu_1 + \mu_2, -2\mu_1 - 3\mu_2] \quad (17)$$

```
> solve(SYSMU, [mu1,mu2]) ;
```

$$\left[\left[\mu_1 = -\frac{3}{5}, \mu_2 = \frac{2}{5} \right] \right] \quad (18)$$

Discard the solution because $\mu_1 < 0$

Discussion of the first point

```
> Hess := <<diff(L,x,x),diff(L,x,y)>|<diff(L,x,y),diff(L,y,y)>> ;
```

$$Hess := \begin{bmatrix} 0 & 1 \\ 1 & 2\mu_1 - 6\mu_2 y \end{bmatrix} \quad (19)$$

```
> subs(SOL1,[g1,g2]) ;
```

$$[1, 1] \quad (20)$$

No constraint is active, the kernel is the whole \mathbb{R}^2

```
> subs(SOL1,Hess) ; LinearAlgebra[Eigenvalues](%) ;
```

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad (21)$$

Discussion of the second point

```
> subs(SOL2,[g1,g2]) ;
```

(22)

$$\left[\frac{7}{4} - \frac{1}{4} 2^{2/3}, 0 \right] \quad (22)$$

The second constraint is active

> gradg2 := subs(SOL2, <diff(g2,x) | diff(g2,y)>) ;

$$\text{gradg2} := \left[-1 \quad \frac{3}{4} 2^{2/3} \right] \quad (23)$$

> Z := op(LinearAlgebra[NullSpace](gradg2)) ;

$$Z := \begin{bmatrix} \frac{3}{4} 2^{2/3} \\ 1 \end{bmatrix} \quad (24)$$

> Hess2 := subs(SOL2, Hess) ;

$$\text{Hess2} := \begin{bmatrix} 0 & 1 \\ 1 & \frac{3}{2} 2^{2/3} \end{bmatrix} \quad (25)$$

> LinearAlgebra[Transpose](Z) . Hess2 . Z ;

$$3 2^{2/3} \quad (26)$$

The point is a minimum, satisfy sufficient condition.

Discussion of the last point

> subs(SOL3, [g1,g2]) ;

$$\left[0, \frac{1}{9} \sqrt{3} + \frac{5}{3} \right] \quad (27)$$

The first constraint is active

> gradg1 := subs(SOL3, <diff(g1,x) | diff(g1,y)>) ;

$$\text{gradg1} := \left[1 \quad -\frac{2}{3} \sqrt{3} \right] \quad (28)$$

> Z := op(LinearAlgebra[NullSpace](gradg1)) ;

$$Z := \begin{bmatrix} \frac{2}{3} \sqrt{3} \\ 1 \end{bmatrix} \quad (29)$$

> Hess3 := subs(SOL3, Hess) ;

$$\text{Hess3} := \begin{bmatrix} 0 & 1 \\ 1 & \frac{2}{3} \sqrt{3} \end{bmatrix} \quad (30)$$

> LinearAlgebra[Transpose](Z) . Hess3 . Z ;

$$2\sqrt{3} \quad (31)$$

The point is a minimum, satisfy sufficient condition.