

Solve a DAE using non stabilized numerical schemes

> **restart:**

The DAE

```
> EQ1 := x(t)-sin(t) ;
EQ2 := diff(x(t),t)+y(t) ;
EQ1 :=  $x(t) - \sin(t)$ 
EQ2 :=  $\frac{d}{dt} x(t) + y(t)$  (1)
```

Reduce the index

```
> DEQ1 := diff(EQ1,t) ;
DEQ1 :=  $\frac{d}{dt} x(t) - \cos(t)$  (2)
```

```
> subs(solve(DEQ1,{diff(x(t),t)}),EQ2) ;
DEQ2 := diff(%,t) ;
DEQ2 :=  $\cos(t) + y(t)$ 
DEQ2 :=  $-\sin(t) + \frac{d}{dt} y(t)$  (3)
```

Approximate solution of the ODE by using Explicit Euler

```
> ODE := {DEQ1,DEQ2} ;
ODE :=  $\left\{ \frac{d}{dt} x(t) - \cos(t), -\sin(t) + \frac{d}{dt} y(t) \right\}$  (1.1)
```

```
> SUBS := diff(x(t), t) = (x[k+1]-x[k])/h,
    diff(y(t), t) = (y[k+1]-y[k])/h,
    cos(t) = cos(k*h),
    sin(t) = sin(k*h) ;
SUBS :=  $\frac{d}{dt} x(t) = \frac{x_{k+1} - x_k}{h}, \frac{d}{dt} y(t) = \frac{y_{k+1} - y_k}{h}, \cos(t) = \cos(kh), \sin(t) = \sin(kh)$  (1.2)
```

```
> ExplicitEuler := subs(SUBS,ODE) ;
ExplicitEuler :=  $\left\{ \frac{x_{k+1} - x_k}{h} - \cos(kh), -\sin(kh) + \frac{y_{k+1} - y_k}{h} \right\}$  (1.3)
```

```
> ExplicitEulerAdvance := solve( ExplicitEuler, {x[k+1],y[k+1]} ) ;
ExplicitEulerAdvance :=  $\{x_{k+1} = x_k + \cos(kh)h, y_{k+1} = \sin(kh)h + y_k\}$  (1.4)
```

```
> T := 10.5*Pi ;
N := 500 ;
h := T/N ;
T :=  $10.5\pi$ 
N := 500
h :=  $0.02100000000\pi$  (1.5)
```

```

> X := [0.1] ;
Y := [1] ;
for k from 1 to N do
  SOLSTEP := subs(x[k]=X[-1],y[k]=Y[-1],ExplicitEulerAdvance) :
  X := [op(X),evalf(subs( SOLSTEP, x[k+1] ))];
  Y := [op(Y),evalf(subs( SOLSTEP, y[k+1] ))];
end;

```

$X := [0.1]$

$Y := [1]$

(1.6)

```
> plot( [seq([X[k],Y[k]],k=1..N)]);
```

