Numerical Methods for Dynamic System and Control del 7/7/2014

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Solve the following optima			
	Minimize: $\int_0^1 x(t) dt = 0$ $x'(t) = x(t) + u$ $x(0) = 0,$	$u(t)^2 dt$ $\iota(t)$	
	(x(0)=0,		
The Boundary Value Pro	blem (BVP):		
The entimal control u(t)			
The optimal control $u(t)$:			
The solution of the BVP:			

Study the following constrained minimization problem.

minimize
$$f(x, y, z) = z + y^2 - x^2$$
, subject to $x = z$, $x \ge 0$, $x \le 1$,

KKT system of first order condition:

$$\begin{cases}
-\mu_1 + \mu_2 - \lambda - 2x &= 0 \\
2y &= 0 \\
\lambda + 1 &= 0 \\
x - z &= 0 \\
x\mu_1 &= 0 \\
(1 - x)\mu_2 &= 0
\end{cases}$$

Solutions of KKT system:

$$\begin{cases} x=0, & y=0, \quad z=0, \quad \lambda=-1, \quad \mu_1=1, \quad \mu_2=0 \\ x=1, & y=0, \quad z=1, \quad \lambda=-1, \quad \mu_1=0, \quad \mu_2=1 \\ x=1/2, & y=0, \quad z=1/2, \quad \lambda=-1, \quad \mu_1=0, \quad \mu_2=0 \end{cases}$$

Discussion of the stationary point: x = 0, y = 0, z = 0, $\lambda = -1$, $\mu_1 = 1$, $\mu_2 = 0$

$$abla[h,g_1] = \begin{pmatrix} 1 & 0 & -1 \\ 1 & 0 & 0 \end{pmatrix} \qquad \boldsymbol{K} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \qquad \boldsymbol{K}^T \nabla^2 \mathcal{L} \boldsymbol{K} = [2]$$

Solve the following recurrence

$$x_{k+1} = y_k + 1, x_0 = 0,$$

$$y_{k+1} = 2x_k - 1, y_0 = 1,$$

 \mathcal{Z} -transform:

$$\zeta x(\zeta) = y(\zeta) + \frac{\zeta}{\zeta - 1},$$

$$\zeta y(\zeta) - \zeta = 2x(\zeta) - \frac{\zeta}{\zeta - 1},$$

Solution in \mathcal{Z} :

$$x(\zeta) = \frac{2\zeta}{\zeta^2 - 2},$$

$$y(\zeta) = \zeta \frac{\zeta^2 - 2\zeta + 2}{(\zeta^2 - 2)(\zeta - 1)} = \frac{2\zeta^2}{\zeta^2 - 2} - \frac{\zeta}{\zeta - 1}$$

Solution in k

$$x_k = \frac{1}{2}(-\sqrt{2})^{k+1} + \frac{1}{2}(\sqrt{2})^{k+1},$$

$$y_k = (-\sqrt{2})^k + (\sqrt{2})^k - 1,$$

Solve using Laplace transform the following boundary value problem

$$x''(t) + y(t) = 1 - \cos t$$

$$y''(t) - x''(t) = \cos t$$

$$x(0) = 1, \quad y(0) = 1, \quad x(\pi/2) = 0, \quad y(\pi/2) = 1,$$

Suggestion: Set A = x'(0) and B = y'(0) then using Laplace transform compute A and B which satisfy the boundary conditions.

The Laplace transform:

$$\begin{cases} s^2 x(s) - A - s + y(s) &= \frac{1}{s} - \frac{s}{s^2 + 1} \\ s^2 y(s) - B - s^2 x(s) + A &= \frac{s}{s^2 + 1} \end{cases}$$

Solution in s with partial fraction expansion:

$$\begin{cases} x(s) = \frac{s^3 + As^2 + A - B}{s^2(s^2 + 1)} = \frac{B + s}{s^2 + 1} + \frac{A - B}{s^2} \\ y(s) = \frac{s^2 + Bs + 1}{s^2(s^2 + 1)} = \frac{B}{s^2 + 1} + \frac{1}{s} \end{cases}$$

Value of A and B:

$$A = 0, \qquad B = 0$$

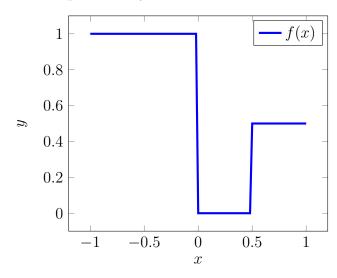
Solution in t:

$$\begin{cases} x(t) = \cos t \\ y(t) = 1 \end{cases}$$

Compute the coefficients of the Fourier series of the following function:

$$f(x) = \begin{cases} 1 & \text{for } -1 \le x < 0 \\ 0 & \text{for } 0 \le x < 1/2 \\ 1/2 & \text{for } 1/2 \le x < 1 \end{cases}$$

defined for $x \in (-1,1)$ and extended periodically.



Coefficients a_k and b_k for the Fourier serie:

$$a_0 = \frac{5}{4}$$

$$a_k = -\frac{\sin(k\pi/2)}{2k\pi} = \frac{1}{2k\pi} \begin{cases} 0 & \text{for } k = 4m \\ -1 & \text{for } k = 4m+1 \\ 0 & \text{for } k = 4m+2 \\ 1 & \text{for } k = 4m+3 \end{cases}$$

$$b_k = -\frac{\cos(k\pi) + \cos(k\pi/2) - 2}{2k\pi} = \frac{1}{2k\pi} \begin{cases} 0 & \text{for } k = 4m \\ -3 & \text{for } k = 4m + 1 \\ -2 & \text{for } k = 4m + 2 \\ -3 & \text{for } k = 4m + 3 \end{cases}$$