

## Constrained minimization

Maximize the volume ( $x=i, y=R$ )

$$\begin{aligned} > \mathbf{f} := -\mathbf{subs}(\mathbf{SUBS}, \mathbf{x*y*z}) ; \text{ Maximize the volume} \\ & \qquad \qquad \qquad f := -xyz \end{aligned} \tag{1}$$

Constraints

$$\begin{aligned} > \mathbf{h} &:= \mathbf{S} - 2*(\mathbf{x*y} + \mathbf{x*z} + \mathbf{y*z}) ; \\ \mathbf{g1} &:= \mathbf{x} \geq \mathbf{0} ; \\ \mathbf{g2} &:= \mathbf{y} \geq \mathbf{0} ; \\ \mathbf{g3} &:= \mathbf{z} \geq \mathbf{0} ; \\ & \qquad \qquad \qquad h := -2xy - 2xz - 2yz + S \\ & \qquad \qquad \qquad g1 := 0 \leq x \\ & \qquad \qquad \qquad g2 := 0 \leq y \\ & \qquad \qquad \qquad g3 := 0 \leq z \end{aligned} \tag{2}$$

$$\begin{aligned} > \mathbf{L} &:= \mathbf{f} - \mathbf{lambda*h} - \mathbf{mu1*rhs(g1)} - \mathbf{mu2*rhs(g2)} - \mathbf{mu3*rhs(g3)} ; \\ & \qquad \qquad \qquad L := -xyz - \lambda(-2xy - 2xz - 2yz + S) - \mu_1 x - \mu_2 y - \mu_3 z \end{aligned} \tag{3}$$

Nonlinear system

$$\begin{aligned} > \mathbf{EQ1} &:= \mathbf{diff(L,x)} ; \\ \mathbf{EQ2} &:= \mathbf{diff(L,y)} ; \\ \mathbf{EQ3} &:= \mathbf{diff(L,z)} ; \\ \mathbf{EQ4} &:= \mathbf{h} ; \\ \mathbf{EQ5} &:= \mathbf{rhs(g1)*mu1} ; \\ \mathbf{EQ6} &:= \mathbf{rhs(g2)*mu2} ; \\ \mathbf{EQ7} &:= \mathbf{rhs(g3)*mu3} ; \\ & \qquad \qquad \qquad EQ1 := -yz - \lambda(-2y - 2z) - \mu_1 \\ & \qquad \qquad \qquad EQ2 := -xz - \lambda(-2x - 2z) - \mu_2 \\ & \qquad \qquad \qquad EQ3 := -xy - \lambda(-2x - 2y) - \mu_3 \\ & \qquad \qquad \qquad EQ4 := -2xy - 2xz - 2yz + S \\ & \qquad \qquad \qquad EQ5 := \mu_1 x \\ & \qquad \qquad \qquad EQ6 := \mu_2 y \\ & \qquad \qquad \qquad EQ7 := \mu_3 z \end{aligned} \tag{4}$$

$$\begin{aligned} > \mathbf{SOL} &:= \mathbf{solve(\{EQ | (1..7)}, \mathbf{x}>\mathbf{0}, \mathbf{y}>\mathbf{0}, \mathbf{z}>\mathbf{0}, \mathbf{mu1}>=\mathbf{0}, \mathbf{mu2}>=\mathbf{0}, \mathbf{mu3}>=\mathbf{0}), \{x,y,} \\ & \qquad \qquad \mathbf{z, lambda, mu1, mu2, mu3}\} ); \\ \mathbf{SOL} &:= \left\{ \lambda = -\frac{1}{24} \sqrt{6} \sqrt{S}, \mu_1 = 0, \mu_2 = 0, \mu_3 = 0, x = -\frac{1}{6} \sqrt{6} \sqrt{S}, y = -\frac{1}{6} \sqrt{6} \sqrt{S}, z = \right. \\ & \qquad \qquad \left. -\frac{1}{6} \sqrt{6} \sqrt{S} \right\}, \left\{ \lambda = \frac{1}{24} \sqrt{6} \sqrt{S}, \mu_1 = 0, \mu_2 = 0, \mu_3 = 0, x = \frac{1}{6} \sqrt{6} \sqrt{S}, y \right. \\ & \qquad \qquad \left. = \frac{1}{6} \sqrt{6} \sqrt{S}, z = \frac{1}{6} \sqrt{6} \sqrt{S} \right\} \end{aligned} \tag{5}$$

$$\begin{aligned} > \mathbf{SOL} &:= \mathbf{SOL[2]} ; \\ \mathbf{SOL} &:= \left\{ \lambda = \frac{1}{24} \sqrt{6} \sqrt{S}, \mu_1 = 0, \mu_2 = 0, \mu_3 = 0, x = \frac{1}{6} \sqrt{6} \sqrt{S}, y = \frac{1}{6} \sqrt{6} \sqrt{S}, z \right. \end{aligned} \tag{6}$$

$$= \frac{1}{6} \sqrt{6} \sqrt{S} \}$$

Check if the solution is a minimum. Compute the gradient of the active constraints

```
> subs(SOL,rhs(g1)) ; # g1 is not active
subs(SOL,rhs(g2)) ; # g2 is not active
subs(SOL,rhs(g3)) ; # g3 is not active
```

$$\frac{1}{6} \sqrt{6} \sqrt{S}$$

$$\frac{1}{6} \sqrt{6} \sqrt{S}$$

$$\frac{1}{6} \sqrt{6} \sqrt{S}$$

(7)

```
> G := subs(SOL,<diff(h,x)|diff(h,y)|diff(h,z)>) ;
```

$$G := \begin{bmatrix} -\frac{2}{3} \sqrt{6} \sqrt{S} & -\frac{2}{3} \sqrt{6} \sqrt{S} & -\frac{2}{3} \sqrt{6} \sqrt{S} \end{bmatrix}$$

(8)

```
> K := op(LinearAlgebra[NullSpace](G)) ;
K := <K[1]|K[2]>;
```

$$K := \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$K := \begin{bmatrix} -1 & -1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}$$

(9)

The hessian of the Lagrangian

```
> H := <<diff(L,x,x),diff(L,x,y),diff(L,x,z)>|
<diff(L,x,y),diff(L,y,y),diff(L,y,z)>|
<diff(L,x,z),diff(L,z,y),diff(L,z,z)>>;
H := subs(SOL,H) ;
```

$$H := \begin{bmatrix} 0 & -z + 2\lambda & -y + 2\lambda \\ -z + 2\lambda & 0 & -x + 2\lambda \\ -y + 2\lambda & -x + 2\lambda & 0 \end{bmatrix}$$

$$H := \begin{bmatrix} 0 & -\frac{1}{12} \sqrt{6} \sqrt{S} & -\frac{1}{12} \sqrt{6} \sqrt{S} \\ -\frac{1}{12} \sqrt{6} \sqrt{S} & 0 & -\frac{1}{12} \sqrt{6} \sqrt{S} \\ -\frac{1}{12} \sqrt{6} \sqrt{S} & -\frac{1}{12} \sqrt{6} \sqrt{S} & 0 \end{bmatrix}$$

(10)

```
> HReduced := LinearAlgebra[Transpose](K).H.K ;
```

$$HReduced := \begin{bmatrix} \frac{1}{6} \sqrt{6} \sqrt{S} & \frac{1}{12} \sqrt{6} \sqrt{S} \\ \frac{1}{12} \sqrt{6} \sqrt{S} & \frac{1}{6} \sqrt{6} \sqrt{S} \end{bmatrix} \quad (11)$$

Use Sylvester criteria

$$> \text{LinearAlgebra[Determinant]}(HReduced[1..1,1..1]) ;$$

$$\frac{1}{6} \sqrt{6} \sqrt{S} \quad (12)$$

$$> \text{LinearAlgebra[Determinant]}(HReduced[1..2,1..2]) ;$$

$$\frac{1}{8} S \quad (13)$$