

RIASSUNTO RK

$$\begin{cases} y' = f(x, y) \\ y(a) = y_a \end{cases}$$

$$\begin{array}{c|c} c & A \\ \hline & b^T \end{array}$$

TABLEAU

AVANZAMENTO

$$y_{n+1} = y_n + \sum_{j=1}^s b_j k_j$$

$$k_j = h f(x_n + c_j h, y_n + \sum_{e=1}^s a_{je} k_e)$$

s = numero di stadi

Se $a_{je} = 0$ per $e > j$
allora il metodo è
esplicito

MODO ALTERNATIVO

$$y_{n+1} = y_n + h \sum_{j=1}^s b_j k_j$$

$$k_j = f(x_n + c_j h, y_n + h \sum_{e=1}^s a_{je} k_e)$$

ALTRO MODO

$$y_{n+1} = y_n + h \sum_{j=1}^s b_j f(\tilde{x}_j, \tilde{y}_j)$$

$$\tilde{x}_j = x_n + c_j h$$

$$\tilde{y}_j = y_n + h \sum_{e=1}^s a_{je} f(\tilde{x}_e, \tilde{y}_e)$$

Relazioni Algebriche per Calcolare Errori Locali

$$y_{k+1} = \psi(x_k, y_k, h)$$

$$y(x_{k+1}) - \psi(x_k, y_k, h) = \tau_k$$

$$|\tau_k| \leq C h^p ?$$

$$\mathbb{1} = \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}$$

CONDIZIONE 0 $\tau_k \rightarrow 0$ $h \rightarrow 0$

$$\sum_{j=1}^s a_{ij} = c_i \quad i=1, 2, \dots, s$$

$$A \mathbb{1} = c$$

$$\begin{array}{c|l} c_1 & \leftarrow \\ c_2 & \leftarrow \\ \vdots & \\ c_s & \leftarrow \end{array}$$

ORDINE 1 $|\tau_k| \leq C h^2$

$$\sum_{j=1}^s b_j = 1$$

$$b \cdot \mathbb{1} = 1$$

ORDINE 2 $|\tau_k| \leq C h^3$

$$\sum_{j=1}^s b_j c_j = \frac{1}{2}$$

$$b \cdot c = \frac{1}{2}$$

ORDINE 3

$|b_n| \in C^4$

$$\sum_{j=1}^s b_j c_j^2 = \frac{1}{3}$$

$$\sum_{i,j=1} b_i \theta_{ij} c_j = \frac{1}{6} \Rightarrow$$

$$\underline{b^T A c} = \frac{1}{6}$$

ORDINE 4

$|b_n| \in C^5$

$$\sum_{j=1}^s b_j c_j^3 = \frac{1}{4} \Rightarrow$$

$$b \cdot c^3 = \frac{1}{4}$$

$$\sum_{i,j=1}^s b_i c_i \theta_{ij} c_j = \frac{1}{8}$$

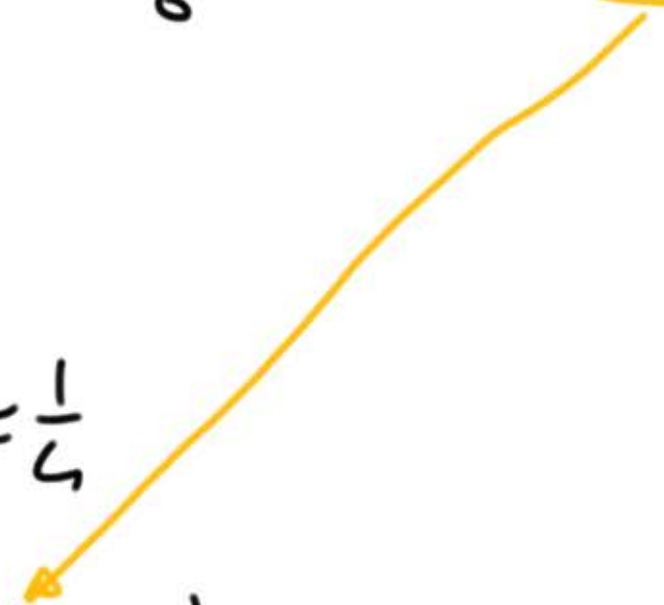
$$(bc) \cdot \underline{Ac} = \frac{1}{8}$$

$$\sum_{i,j=1}^s b_i \theta_{ij} c_j^2 = \frac{1}{12}$$

$$b \cdot (Ac^2) = \frac{1}{12}$$

$$\sum_{i,j,\kappa=1}^s \underbrace{b_i \theta_{ij}}_{b^T A} \underbrace{\theta_{j\kappa}}_{Ac} c_\kappa = \frac{1}{24}$$

$$(A^T b) \cdot \underline{(Ac)} = \frac{1}{24}$$



ESEMPIO (RALSTON METHOD)

$$\begin{array}{c|cc} 0 & 1 & 1 \\ \hline 2/3 & 2/3 & 3/4 \end{array} \quad \begin{array}{l} \text{METODO ESPlicito} \\ \text{0} \end{array}$$

CONSISTENZA

$$c_1 = 0 = \theta_{11} + \theta_{12} = 0 + 0 = 0 \quad (\text{OK})$$

$$c_2 = 2/3 = \theta_{21} + \theta_{22} = 2/3 + 0 = 2/3 \quad (\text{OK})$$

ORDINE 1

$$b_1 + b_2 = 1/4 + 3/4 = 1 \quad (\text{OK})$$

ORDINE 2

$$b \cdot c = \begin{pmatrix} 1/4 \\ 3/4 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 2/3 \end{pmatrix} = 1/2 \quad (\text{OK})$$

ORDINE = 2

ORDINE 3

$$b \cdot c^2 = \begin{pmatrix} 1/4 \\ 3/4 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 4/9 \end{pmatrix} = \frac{1}{3} \quad (\text{OK}) \quad A_c = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad b \cdot A_c = 0 \quad (\text{NO})$$

ESSENCIO APPLICATIONI

$$\begin{cases} y' = x^2 + e^y \\ y(0) = 1 \end{cases}$$

$$\begin{array}{c|cc} 0 & \cdot & \cdot \\ \hline 2/3 & 2/3 & \cdot \\ \hline 1/4 & 3/4 & \end{array}$$

Metodo RK

$$y_{n+1} = y_n + \frac{1}{4} k_1 + \frac{3}{4} k_2$$

$$\begin{aligned} k_1 &= h f(x_n + c_1 h, y_n + \sum_{j=1}^2 a_{1j} k_j) = h f(x_n, y_n) \\ &= h (x_n^2 + e^{y_n}) \end{aligned}$$

$$\begin{aligned} k_2 &= h f(x_n + c_2 h, y_n + \sum_{j=1}^2 a_{2j} k_j) = h f(x_n + \frac{2}{3} h, y_n + \frac{2}{3} k_1) \\ &= (x_n + \frac{2}{3} h)^2 + e^{y_n + \frac{2}{3} k_1} \end{aligned}$$

ESTENSIONE AL CASO VETTORIALE

$$\begin{cases} Y' = F(x, Y) \\ Y(0) = Y_0 \end{cases} \quad Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} \quad F(x, Y) = \begin{pmatrix} f_1(x, y_1, y_2, \dots, y_n) \\ f_2(x, y_1, y_2, \dots, y_n) \\ \vdots \\ f_n(x, y_1, y_2, \dots, y_n) \end{pmatrix}$$

Tutte le formule, metodi visti fino ad ora
valgono nel caso vettoriale

Esempio (Euler esplicito)

$$Y_{k+1} = Y_k + h f(x_k, Y_k)$$

$$Y(x_{k+1}) - Y(x_k) - h f(x_k, Y(x_k)) = \tau_k \\ |\tau_k| \leq c h^2$$

$$Y_{k+1} = Y_k + h F(x_k, Y_k)$$

$$Y(x_{k+1}) - Y(x_k) - h F(x_k, Y(x_k)) = \vec{\tau}_k$$

$$\|\vec{\tau}_k\| \leq c h^2$$

Esempio di vettore

$$\begin{cases} x'(t) = y(t) \\ y'(t) = -x(t) \\ x(0) = 1 \\ y(0) = 0 \end{cases} \quad z = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$F(t, z) = \begin{pmatrix} z_2 \\ -z_1 \end{pmatrix} = \begin{pmatrix} y \\ -x \end{pmatrix}$$

$$z(t+1) = \begin{pmatrix} x(t+1) \\ y(t+1) \end{pmatrix}$$

H

$$\begin{cases} z' = F(t, z) = \begin{pmatrix} z_2 \\ -z_1 \end{pmatrix} \\ z(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{cases}$$

$$g(t) = x(t)^2 + y(t)^2$$

$$g'(t) = 2x(t)x'(t) + 2y(t)y'(t)$$

$$= 2x(t)y(t) - 2y(t)x(t) = 0$$

Eulero esplicito

$$z_{k+1} = z_k + h F(t_k, z_k)$$

$$g(t) = c \quad \underbrace{x(t)^2 + y(t)^2 = c}_{\text{cerchio}}$$

$$\begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} = \begin{pmatrix} x_k \\ y_k \end{pmatrix} + h \begin{pmatrix} y_k \\ -x_k \end{pmatrix}$$

$$\begin{cases} x_{k+1} = x_k + h y_k \\ y_{k+1} = y_k - h x_k \end{cases}$$

Euler implicito

$$z_{k+1} = z_k + h F(t_{k+1}, z_{k+1})$$

$$\begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} = \begin{pmatrix} x_k \\ y_k \end{pmatrix} + h \begin{pmatrix} y_{k+1} \\ -x_{k+1} \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & -h \\ h & 1 \end{pmatrix} \begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} = \begin{pmatrix} x_k \\ y_k \end{pmatrix}$$

\uparrow
 $\det = 1 + h^2 > 0$

ESERCIZIO:

Scrivere passo un quadraturante per metodo RK di Heun e Colatz

Domanda che succede a $g(t)$ integrato primo nella sua versione discreta?

$$g_n = x_n^2 + y_n^2$$

Caso $\tau \in \text{ceros}$ esplicito

$$g_k = x_k^2 + y_k^2 \quad g_{k+1} ?$$

$$x_{k+1} = x_k + \ell y_k \quad (x_k)$$

$$y_{k+1} = y_k - \ell x_k \quad (y_k)$$

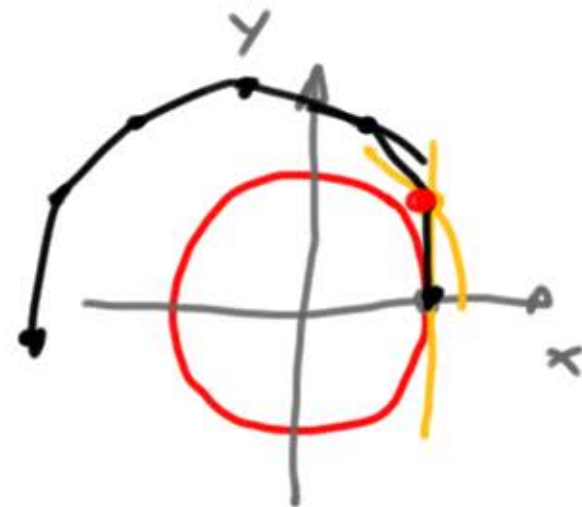
$$x_k x_{k+1} + y_k y_{k+1} = x_k^2 + y_k^2$$

$$\begin{pmatrix} x_k \\ y_k \end{pmatrix} \cdot \begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} = \left\| \begin{pmatrix} x_k \\ y_k \end{pmatrix} \right\|^2$$

$$\leq \left\| \begin{pmatrix} x_k \\ y_k \end{pmatrix} \right\| \left\| \begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} \right\|$$

$$\Rightarrow \left\| \begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} \right\| \geq \left\| \begin{pmatrix} x_k \\ y_k \end{pmatrix} \right\|$$

$$|\alpha \cdot \beta| \leq \|\alpha\| \|\beta\|$$



Esercizio

con Eulero implicito

$$\left\| \begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} \right\| \leq \left\| \begin{pmatrix} x_k \\ y_k \end{pmatrix} \right\|$$

STABILITÀ

Si studia il comportamento di un metodo numerico sulle particolari ODE

$$\begin{cases} y' = dy \\ y(0) = 1 \end{cases}$$

con d numero complesso.

PERCHÉ?

$$z' = F(t, z)$$

cerco adattamento metodo numerico e soluzione esatta in un intorno di (t_0, z_0)

$$z' = A(z - z_0) + b(t - t_0)$$

\Rightarrow LINEARE t_0

$$w = z - z_0$$

$$w' = Aw + b(t - t_0)$$

$$F(t, z) = F(t_0, z_0) + \boxed{\frac{\partial F}{\partial t}(t_0, z_0)} (t - t_0) + \boxed{\frac{\partial F}{\partial z}(t_0, z_0)} (z - z_0) + F$$

Se $b=0$ possiamo studiare una ODE del tipo

$$W' = AW$$

Se A è matrice **DIAGONALIZZABILE** cioè
esiste matrice T tale che

$$T^{-1}AT = \Lambda \quad \Lambda = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_n \end{pmatrix}$$

(Gli argomenti seguenti si possono adottare nel caso
 A non sia diagonalizzabile usando lo forma normale
di Jordan)

$$T^{-1}W' = T^{-1}AW \quad TV = W \quad (\text{cambio di variabile})$$

$$T^{-1}TV' = T^{-1}ATV$$

$$V' = \Lambda V \Rightarrow$$

$$\begin{cases} v'_1 = \lambda_1 v_1 \\ v'_2 = \lambda_2 v_2 \\ \vdots \\ v'_n = \lambda_n v_n \end{cases}$$

n - ODE

disaccoppiate

λ possono essere
complessi

STABILITÀ PER EULER ESPlicito

$$\begin{cases} y' = \alpha y \\ y(0) = 1 \end{cases} \Rightarrow \text{Soluzione esatta} \quad y(x) = e^{\alpha x} \quad (\text{anche se } \alpha \text{ complesso})$$
$$y'(x) = \alpha e^{\alpha x} = \alpha y(x)$$

nel caso α complesso

$$e^{\alpha x} = e^{\operatorname{Re}(\alpha)x} (\cos \operatorname{Im}(\alpha)x + i \sin \operatorname{Im}(\alpha)x)$$

$$|e^{\alpha x}| \rightarrow 0 \quad \text{se} \quad \operatorname{Re}(\alpha) < 0 \quad \operatorname{Re}(\alpha) = 0 \quad |e^{\alpha x}| = 1$$
$$\operatorname{Re}(\alpha) > 0 \quad |e^{\alpha x}| \rightarrow \infty$$

$$Y_{n+1} = Y_n + h \alpha Y_n = (1 + \alpha h) Y_n$$

Domanda $Y_n \rightarrow ?$
 $n \rightarrow \infty$

Vorremmo che
 $Y_n \rightarrow 0$ se $\operatorname{Re}(\alpha) < 0$
Succede sempre?