

COORDINATE PARTITION FOR DAE

EXAMPLE (PENDULUM)

$$m x'' + 2x\lambda = 0$$

$$m y'' + 2y\lambda = -mgy$$

$$x^2 + y^2 = r^2$$

setting $\rho = -2\lambda/m$

$$x'' = \rho x$$

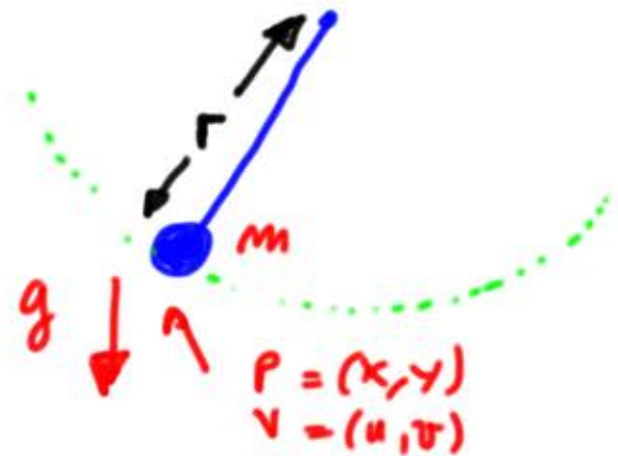
$$y'' = \rho y - g$$

$$x^2 + y^2 = r$$

setting $u = x'$ $v = y'$ transform to 1st order ODE

$$\left\{ \begin{array}{l} x' = u \\ y' = v \\ u' = \rho x \\ v' = \rho y - g \\ x^2 + y^2 = r^2 \end{array} \right.$$

DAE FOR THE PENDULUM



COMPUTE THE DIFFERENTIAL INDEX

$$g(x, y) = x^2 + y^2 - r^2 \quad (\text{constraint})$$

$$\frac{d}{dt} g(x(t), y(t)) = \frac{\partial g}{\partial x} x' + \frac{\partial g}{\partial y} y' = 2x x' + 2y y' = \underbrace{2xu + 2yv}_{\text{algebraic}}$$

$$\begin{cases} x' = u \\ y' = v \\ u' = \rho x \\ v' = \rho y - g \\ x^2 + y^2 = r^2 \end{cases}$$

$$\begin{aligned} \left(\frac{d}{dt}\right)^2 g(x, y) &= 2x'u + 2xu' + 2y'v + 2yv' \\ &= 2u^2 + 2\rho x^2 + 2v^2 + 2\rho y^2 - 2yg \end{aligned}$$

$$= 2(u^2 + v^2) + 2\rho(x^2 + y^2) - 2yg \quad \leftarrow \text{algebraic}$$

$$\left(\frac{d}{dt}\right)^3 g(x, y) = 4(uu' + vv') + 2\rho'(x^2 + y^2) + 4\rho(xx' + yy') - 2y'g$$

$$= 4\rho(xu + yv) - 4vg + 2\rho'(x^2 + y^2) + 4\rho(xu + yv) - 2vg$$

$$= 8\rho(xu + yv) - 6vg + 2\rho'(x^2 + y^2)$$

$$\Rightarrow \rho' = \frac{3vg - 4\rho(xu + yv)}{r^2}$$

\Rightarrow DAE is of INDEX 3

STABILIZATION USING BAUMGART

a) $g(x, y) = x^2 + y^2 - r^2$

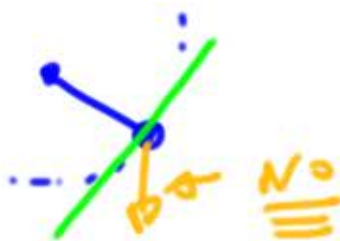
b) $\frac{d}{dt} g(x, y) = 2xu + 2yv$

c) $\left(\frac{d}{dt}\right)^2 g(x, y) = 2(u^2 + v^2) + 2p \underbrace{(x^2 + y^2)}_{r^2} - 2\gamma g$

← HIDDEN CONSTRAINT

(a) ⇒ BE ON THE CIRCLE

(b) ⇒ $2 \begin{pmatrix} x \\ y \end{pmatrix} \cdot \begin{pmatrix} u \\ v \end{pmatrix} \Rightarrow$ velocity orthogonal to the ray



(c) ⇒ $p = \frac{\gamma g - (u^2 + v^2)}{r^2}$ p is proportional to centripetal force

$$\left(\frac{d}{dt}\right)^2 g(x, y) + 2\eta\omega \frac{d}{dt} g(x, y) + \omega^2 g(x, y) = 0$$

⇒ $p = p(x, y, u, v)$

$$\boxed{0 \leq \eta \leq 1 \quad \omega \geq 0}$$

$$\begin{cases} x' = u \\ y' = v \\ u' = \nu x \\ v' = \nu y - g \\ x^2 + y^2 = r^2 \end{cases}$$

INDEX - 3

DAE

USING

BAUM 4+2π =

⇒

$$\begin{cases} x' = u \\ y' = v \\ u' = \nu x \\ v' = \nu y - g \\ \nu = \nu(x, y, u, v) \end{cases}$$

INDEX - 1

DAE

Usually constraint cannot be explicitly solved

$$\left(\frac{d}{dt}\right)^2 g + 2\eta\omega \left(\frac{d}{dt}\right)g + \omega^2 g = 2(u^2 + v^2) + 2\nu(x^2 + y^2) - 2\gamma g$$

$$4\eta\omega(xu + yv) + \omega^2(x^2 + y^2 - r^2) = 0$$

$$\Rightarrow \nu = \frac{\gamma g - (u^2 + v^2) - 2\eta\omega(xu + yv) - \frac{\omega^2}{2}(x^2 + y^2 - r^2)}{x^2 + y^2}$$

$$\begin{cases} x' = u \\ y' = v \\ u' = \nu(x, y, u, v) x \\ v' = \nu(x, y, u, v) y - g \end{cases}$$

DAE

COORDINATE PARTITION APPROACH

$$\begin{cases} x' = u \\ y' = v \\ u' = \nu x \\ v' = \nu y - g \end{cases}$$

$x^2 + y^2 = r^2$

PARTITION (x, y) IN TWO SET

DEPENDENT

INDEPENDENT COORDINATES

y dependent $\Rightarrow y(x, u, v)$

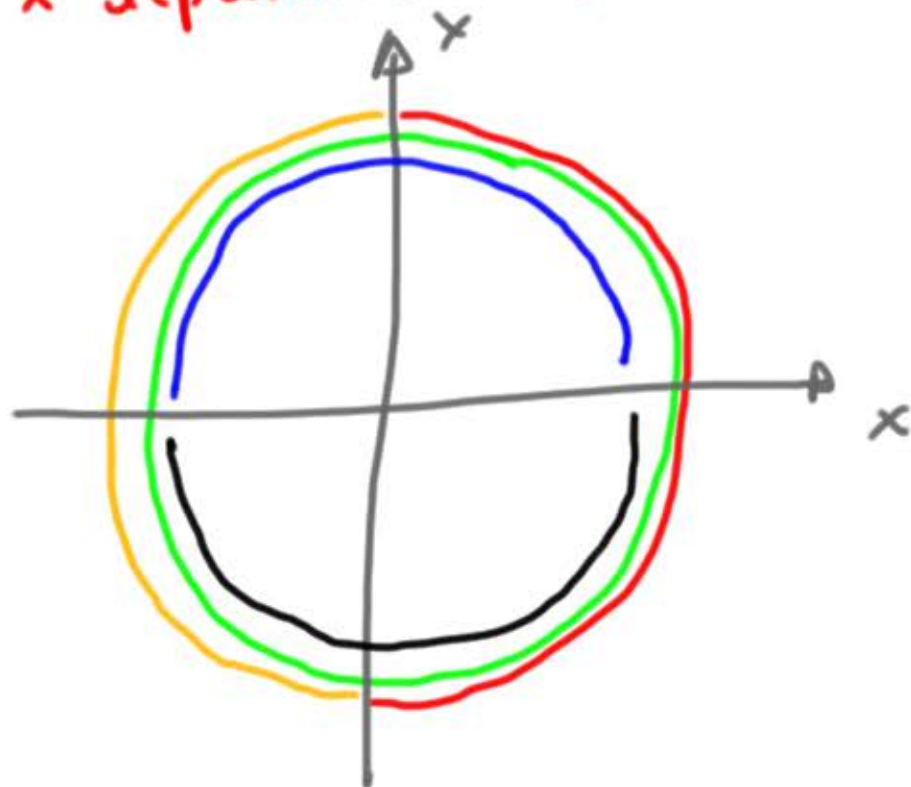
x dependent $\Rightarrow x(y, u, v)$

$$x(y) = +\sqrt{r^2 - y^2}$$

$$x(y) = -\sqrt{r^2 - y^2}$$

$$y(x) = +\sqrt{r^2 - x^2}$$

$$y(x) = -\sqrt{r^2 - x^2}$$



Now USE MAP

$$\begin{cases} x' = u \\ y' = v \\ u' = \mu x \\ v' = \mu y - g \\ x^2 + y^2 = r^2 \end{cases}$$

$$y(x) = -\sqrt{r^2 - x^2}$$

$$\Delta \quad x^2 + y(x)^2 = x^2 + r^2 - x^2 = r^2$$

using this map $y(t) = \underset{\text{def}}{y}(x(t))$

$$x'(t) = u(t)$$

$$y'(t) = \frac{d}{dt} y(t) = \frac{d}{dt} y(x(t)) = \frac{\partial y}{\partial x}(x(t)) x'(t) = v(t)$$

$$\frac{\partial y}{\partial x} = -\frac{\partial}{\partial x} \sqrt{r^2 - x^2} = \frac{x}{\sqrt{r^2 - x^2}}$$

$$\frac{x}{\sqrt{r^2 - x^2}} x' = v$$

\Rightarrow

$$\begin{cases} x' = u \\ x x' = \sqrt{r^2 - x^2} v \Rightarrow x u = \sqrt{r^2 - x^2} v \\ u' = \mu x \\ v' = \mu y(x) - g \end{cases}$$

$$v = v(x, u) = \frac{x u}{\sqrt{r^2 - x^2}}$$

$$\begin{cases} x' = u \\ y' = v \\ u' = \rho x \\ v' = \rho y - y \end{cases}$$

$$\boxed{x^2 + y^2 = r^2}$$

$$y(x) = -\sqrt{r^2 - x^2}$$

\Rightarrow

$$\begin{cases} x' = u \\ u' = \rho x \\ \rho' = \rho y(x) - y \\ y(x) = -\sqrt{r^2 - x^2} \\ v(x, u) = \frac{xu}{\sqrt{r^2 - x^2}} \end{cases}$$

$$\rho' = \frac{d}{dt} v(x, u) = \frac{\partial v}{\partial x} x' + \frac{\partial v}{\partial u} u' = \frac{ur^3}{(r^2 - x^2)^{3/2}} x' + \frac{x}{\sqrt{r^2 - x^2}} u'$$

$$= \frac{r^2 u^2}{(r^2 - x^2)^{3/2}} + \frac{\rho x^2}{\sqrt{r^2 - x^2}}$$

$$\rho' = \rho y(x) - y \Rightarrow \rho = \frac{g(r^2 - x^2)^{3/2} + r^2 u^2}{r^2(x^2 - r^2)} = \rho(x, u)$$

$$\Rightarrow \begin{cases} x' = u \\ u' = \rho(x, u)x \end{cases}$$

$\rho(x, u)$

Δ

This one is valid for
 $-1 < x < +1$
 $-1 < y < 0$

$$\begin{cases} x' = u \\ y' = v \\ u' = \rho x \\ v' = \rho y - g \end{cases}$$

$$x(y) = +\sqrt{r^2 - y^2} \quad \square$$

$$\Delta x(y)^2 + y^2 = r^2 - y^2 + y^2 = r^2$$

using this map $x(t) = x(y(t))$
det

$$x'(t) = \frac{d}{dt} x(y(t)) = \frac{\partial x}{\partial y} y' = \frac{-y}{\sqrt{r^2 - y^2}} v = \frac{-yv}{\sqrt{r^2 - y^2}}$$

$$\Rightarrow u = \frac{-yv}{\sqrt{r^2 - y^2}} \Rightarrow u(y, v) = \frac{-yv}{\sqrt{r^2 - y^2}}$$

$$\begin{cases} y' = v \\ \frac{d}{dt} u(y, v) = \rho x(y) \\ v' = \rho y - g \\ x(y) = \sqrt{r^2 - y^2} \end{cases}$$

$$\begin{cases} x' = u \\ y' = v \\ u' = \rho x \\ r' = \rho y - g \\ x^2 + y^2 = r^2 \end{cases} + y(x) = \sqrt{r^2 - x^2}$$

$$\Rightarrow \begin{cases} y' = v & u(y, v) = -\frac{y v}{\sqrt{r^2 - y^2}} \\ \frac{d}{dt} u(y, v) = \rho x(y) \\ r' = \rho y - g \\ x(y) = \sqrt{r^2 - y^2} \end{cases}$$

$$u' = \frac{d}{dt} u(y, v) = \frac{\partial u}{\partial y} y' + \frac{\partial u}{\partial v} v' = -\frac{\rho r^2 y'}{(r^2 - y^2)^{3/2}} - \frac{y}{\sqrt{r^2 - y^2}} v'$$

$$u' = \rho x \Rightarrow \rho = \frac{v^2}{y^2 - r^2} - \frac{g y}{r^2} = \rho(y, v)$$

$$\Rightarrow \begin{cases} y' = v \\ r' = \rho(y, v) y - g \end{cases}$$

This one is valid for $-1 < x < 1$ and $0 < y < 1$

MINIMAL COORDINATE APPROACH

$$\begin{cases} x' = u \\ y' = v \\ u' = \rho x \\ v' = \rho y - g \\ x^2 + y^2 = r^2 \end{cases}$$

New coordinate θ and x and y are function of θ

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$x(t) = r \cos \theta(t)$$

$$x'(t) = -r \sin \theta(t) \theta'(t) = u$$

$$y(t) = r \sin \theta(t)$$

$$y'(t) = r \cos \theta(t) \theta'(t) = v$$

$$\begin{cases} -r \sin \theta \theta' = u \\ r \cos \theta \theta' = v \\ u' = \rho r \cos \theta \\ v' = \rho r \sin \theta - g \end{cases}$$

$$\begin{matrix} \sin \theta \\ \cos \theta \end{matrix} \Rightarrow r (\sin^2 \theta + \cos^2 \theta) \theta' = v \cos \theta - u \sin \theta$$

$$\theta' = \frac{1}{r} (v \cos \theta - u \sin \theta)$$

$$u' = \frac{d}{dt} (-r \sin \theta \theta') = -r (\cos \theta (\theta')^2 + \sin \theta \theta'')$$

$$v' = \frac{d}{dt} (r \cos \theta \theta') = r (-\sin \theta (\theta')^2 + \cos \theta \theta'')$$

$$\begin{cases} -\Gamma \sin \theta \theta' = u \\ \Gamma \cos \theta \theta' = v \end{cases} \quad \begin{matrix} \sin \theta \\ \cos \theta \end{matrix} \rightarrow \mathcal{P} \quad \begin{matrix} \Gamma (\sin^2 \theta + \cos^2 \theta) \theta' = \\ v \cos \theta - u \sin \theta \end{matrix}$$

$$\begin{cases} u' = \mu \Gamma \cos \theta \\ v' = \mu \Gamma \sin \theta - g \end{cases} \quad \theta' = \frac{1}{\Gamma} (v \cos \theta - u \sin \theta)$$

$$\begin{aligned} \text{(A)} \quad u' &= \frac{d}{dt} (-\Gamma \sin \theta \theta') = -\Gamma (\cos \theta (\theta')^2 + \sin \theta \theta'') = \mu \Gamma \cos \theta && (-\sin \theta) \\ \text{(B)} \quad v' &= \frac{d}{dt} (\Gamma \cos \theta \theta') = \Gamma (-\sin \theta (\theta')^2 + \cos \theta \theta'') = \mu \Gamma \sin \theta - g && (\cos \theta) \end{aligned}$$

$$- \text{(A)} \sin \theta + \text{(B)} \cos \theta = \Gamma \theta'' = \underline{\underline{-g \cos \theta}}$$

SIMPLE CASES

COORDINATE PARTITION FOR INDEX-1 DAE
IN SEMI-EXPLICIT FORM

$$\begin{aligned}x &= (x_1, x_2, \dots, x_m) \\ y &= (y_1, y_2, \dots, y^m)\end{aligned}$$

$$\begin{cases} x' = f(x, y) \\ 0 = g(x, y) \end{cases} \quad \text{where } \frac{\partial g}{\partial y}(x, y) \text{ is square and non singular}$$

Can use implicit functions to write $y(x)$

$$g(x, y) = 0 \Rightarrow \text{find } y(x) \text{ such that } g(x, y(x)) = 0$$

\Rightarrow FORMULA

$$x' = f(x, y(x))$$

$$y(x) = \text{the solution of } g(x, y) = 0$$

COORDINATE PARTITION FOR INDEX-2 DAE IN SEMI EXPLICIT FORM

$$\left\{ \begin{array}{l} \dot{x}' = f(x, y) \\ 0 = g(x) \end{array} \right. \quad \frac{\partial g}{\partial x} \text{ must be full rank}$$

\Rightarrow we can partition x in 2 set
 $x_1 \quad x_2$ such that

$$g(x) = g(x_1, x_2) = 0$$

$$x_2(x_1) \Rightarrow g(x_1, x_2(x_1)) = 0$$

$$\dot{x}' = f(x, y) \Rightarrow \begin{cases} \dot{x}'_1 = f_1(x_1, x_2, y) \\ \dot{x}'_2 = f_2(x_1, x_2, y) \end{cases}$$

$$\dot{x}'_2 = \frac{d}{dt} x_2(x_1(t)) = \frac{\partial x_2}{\partial x_1} \dot{x}'_1(t)$$

$$= \frac{\partial x_2}{\partial x_1} f_1(x_1, x_2, y)$$

$$\frac{\partial x_2}{\partial x_1} f_1(x_1, x_2(x_1), y) = f_2(x_1, x_2(x_1), y)$$

\Rightarrow ALGEBRAIC EQUATION FOR y

Example with index -2 DAE

$$\begin{cases} x' = -y \\ 0 = x - \sin(t) \end{cases}$$

$$\begin{aligned} x' - \cos(t) &= 0 & -y - \cos(t) &= 0 \\ -y' + \sin(t) &= 0 & \Rightarrow \text{INDEX} &= -2 \end{aligned}$$

independent \Rightarrow empty set

dependent $x = 0 \quad x(t) = \sin t$

$$x' = \cos t \quad \Rightarrow \quad y = -\cos t$$

\Rightarrow PATHOLOGICAL IZK APPLIE
ALGEBRAIC EQUATION
DAS LIEF TO AN INDEX -2 DAE